



University of  
**Nottingham**

UK | CHINA | MALAYSIA

# LECTURE 2B

## Alternating Current

### Electromechanical Devices

MMME2051

Module Convenor – Surojit Sen



- Fundamentals of **Alternating Current – or AC**
  - DC v AC circuit study – waveforms a **function of time!**
  - **Sinusoidal** waveform – voltage & current
  - **Complex Numbers**
- AC circuits
  - **Phasor** study – simple way to solve time-varying circuits
  - Resistor, Inductor, Capacitor in phasor form - **CIVIL**
  - **Reactance** – Purely reactive circuits (just inductor/capacitor)
  - **Impedance** – Resistance & Reactance
- Power in AC circuits
  - **Active v Reactive v Apparent Power**
  - **Power Factor**
  - **Resonance**

## Direct Current

Current flowing in only one direction

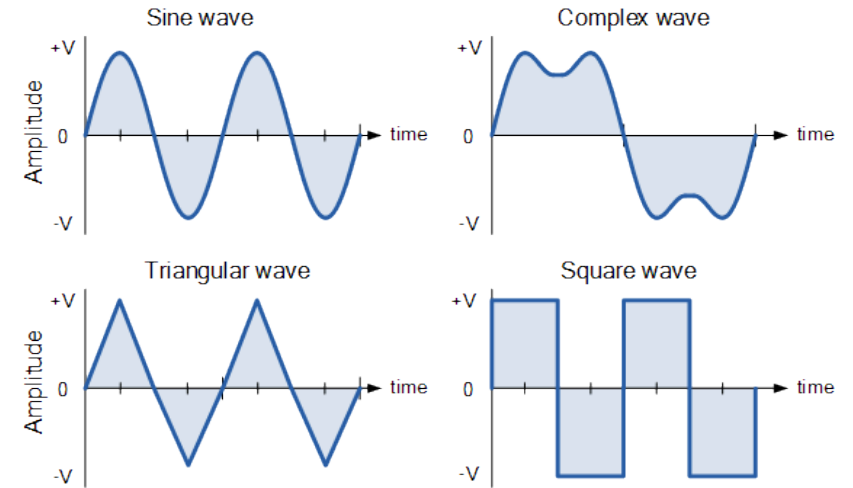
e.g., battery



## Alternating Current

Direction of current flow changes periodically

e.g., generator



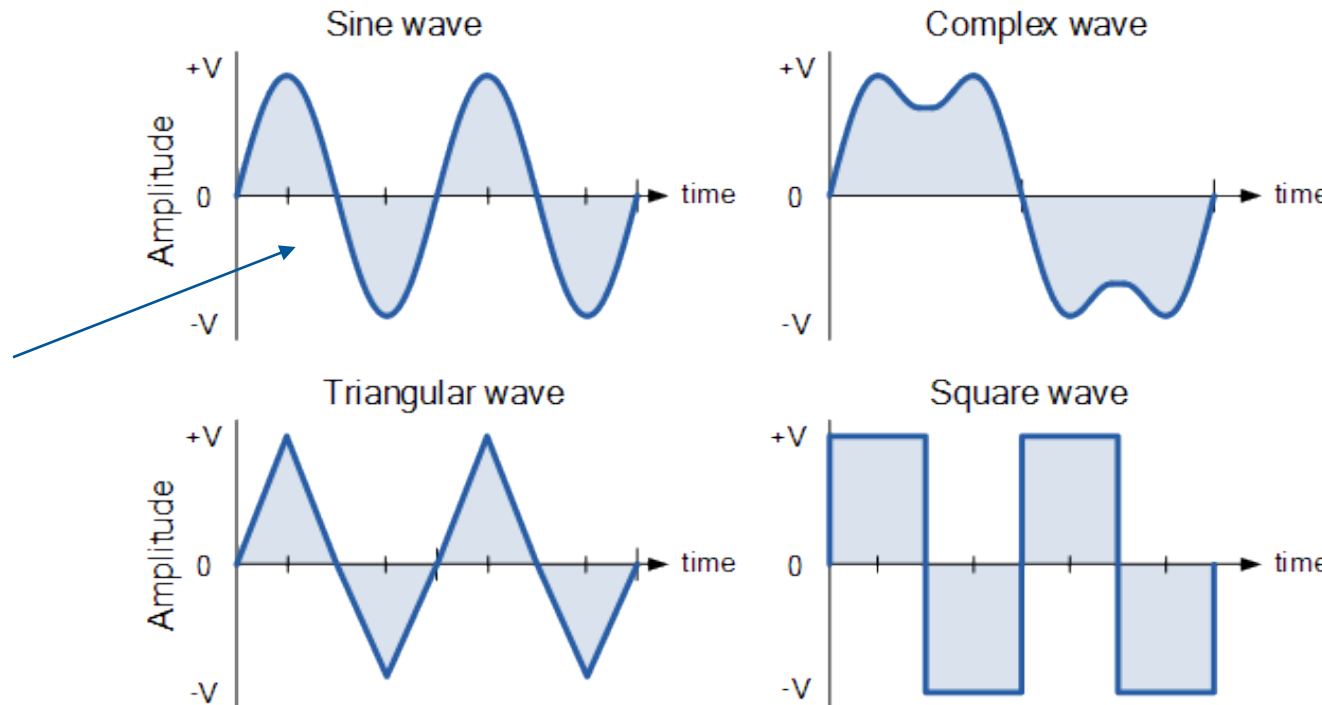
**Abbreviations AC and DC are often used to mean simply alternating and direct, i.e., reference to just current dropped e.g., AC voltage, DC current etc.**



Representation of any **physical variable** as a **function of time** on a **graph**  
(We would discuss only electrical variables like voltage and current)

**Magnitude** (y-axis) and **time** (x-axis)

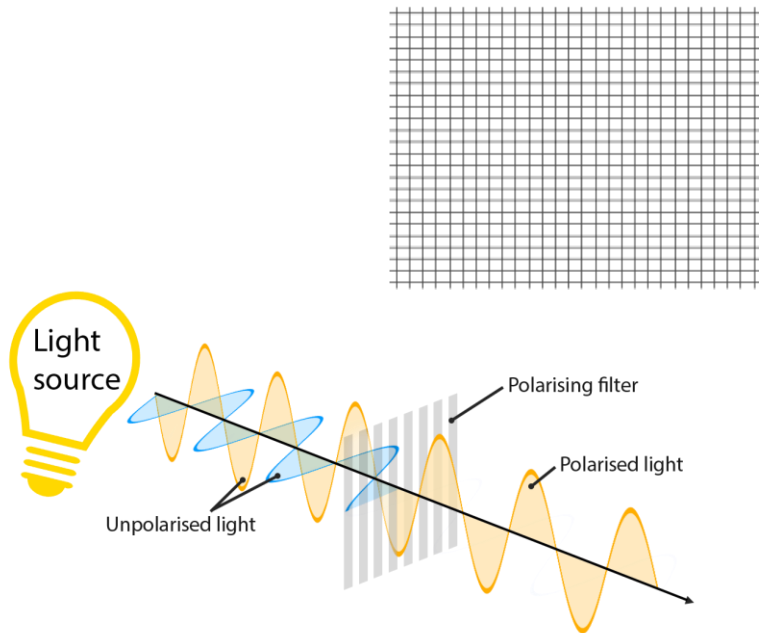
Sine Wave (or sinusoid) is the most interesting – we would be studying this



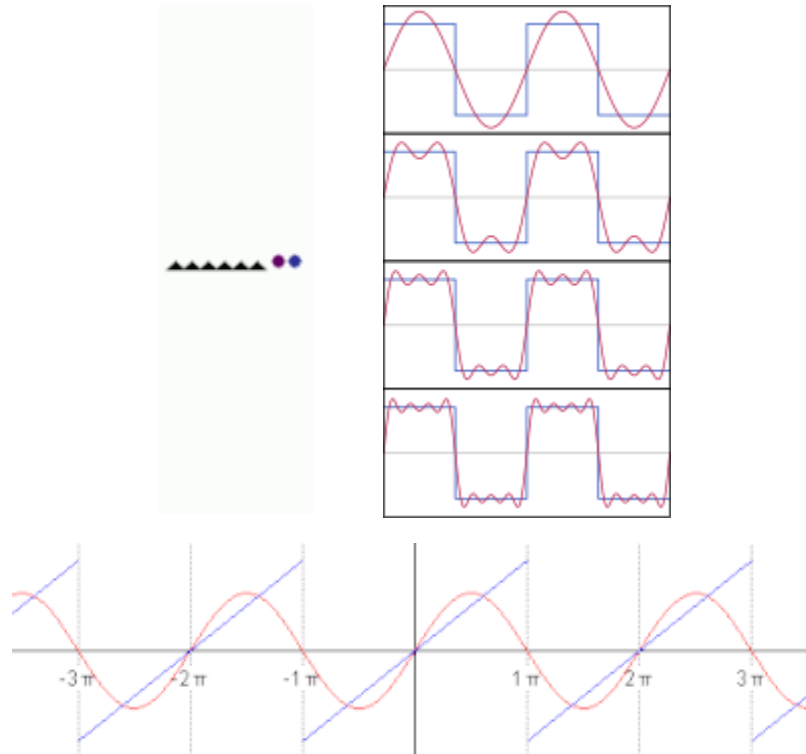
Other waveforms like **triangular**, **sawtooth**, and **square** are abundantly used in electrical engineering – they can all be represented as a sum of infinite number of sinusoids (check out **Fourier Series!**)

## Why is Sine wave interesting?

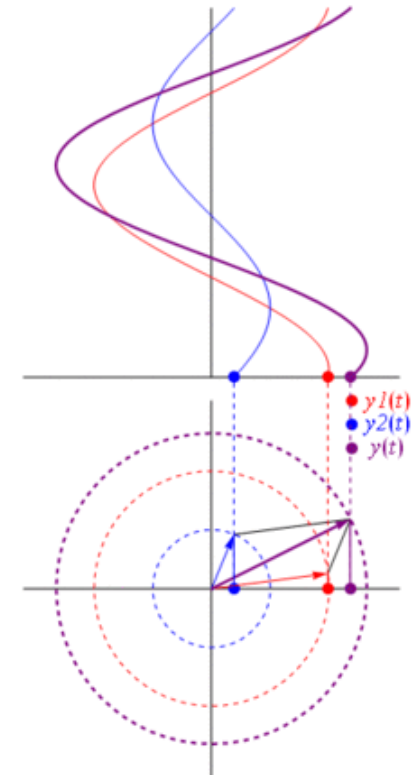
- Occurs in **nature**
- Wind, sound** and **light** waves are sinusoidal



**Fourier Series** – Every waveform is made up of sinusoids



Motors & Generators translate rotation and voltage – **projection of a rotating object is a sinusoid!**



**Sinusoid** is a mathematical curve defined in terms of the **sine trigonometric function**

**Sine** and **Cosine** are both examples of sinusoid

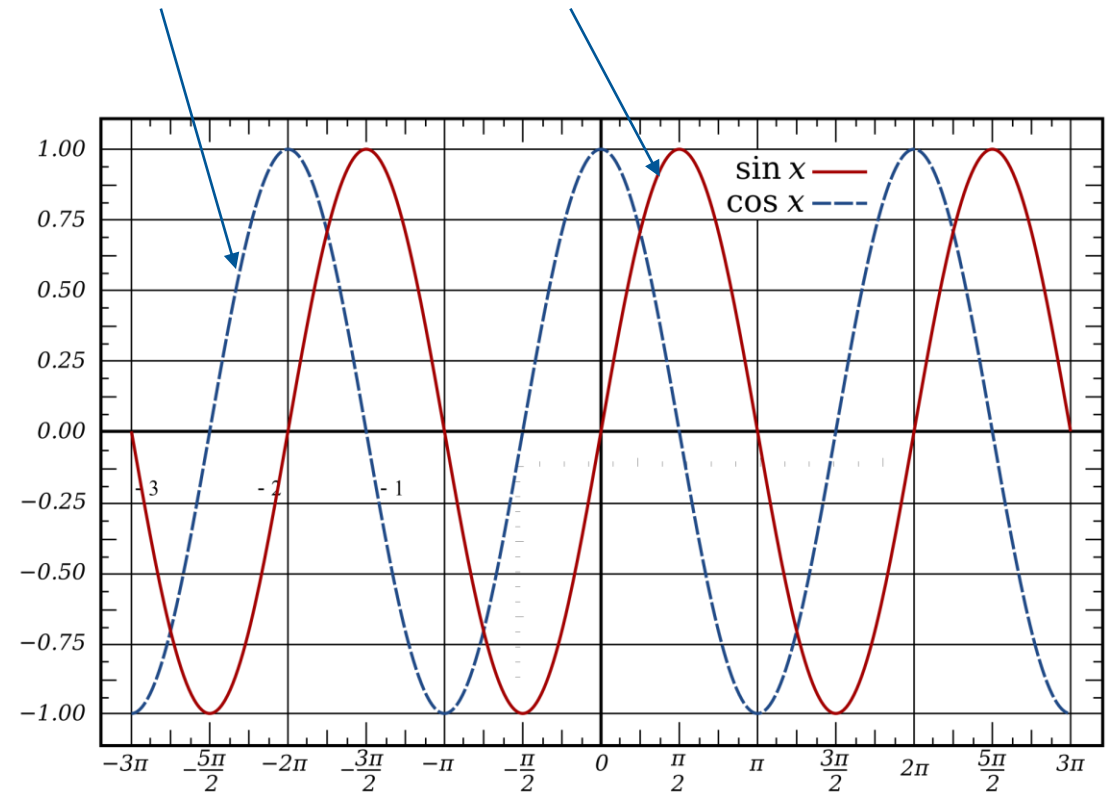
**Cosine** function is simply the Sine function, but **90° advanced**

We will use the **Cosine** function to represent variables

$$y(t) = A \cos(\omega t + \phi)$$

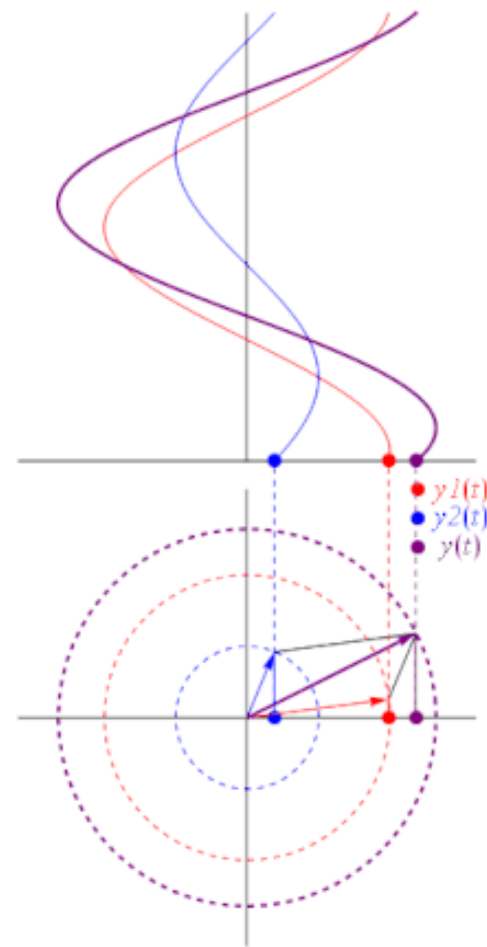
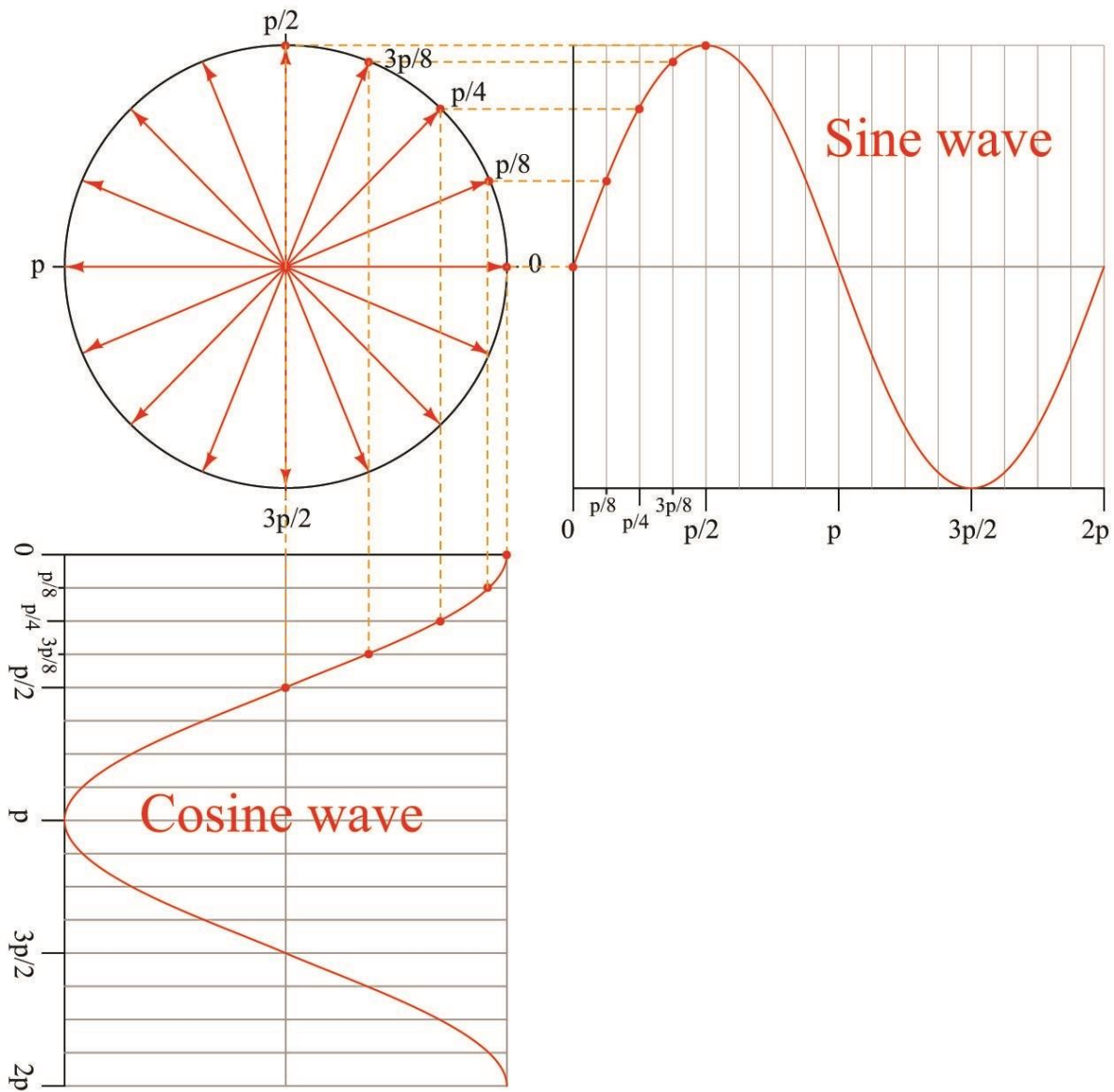
Variable as function of time (points to  $y(t)$ )  
 Amplitude (points to  $A$ )  
 Frequency (points to  $\omega$ )  
 Phase Angle (points to  $\phi$ )  
 Phase offset (points to  $\phi$ )

$$x_1(t) = \cos t \quad x_2(t) = \sin t$$



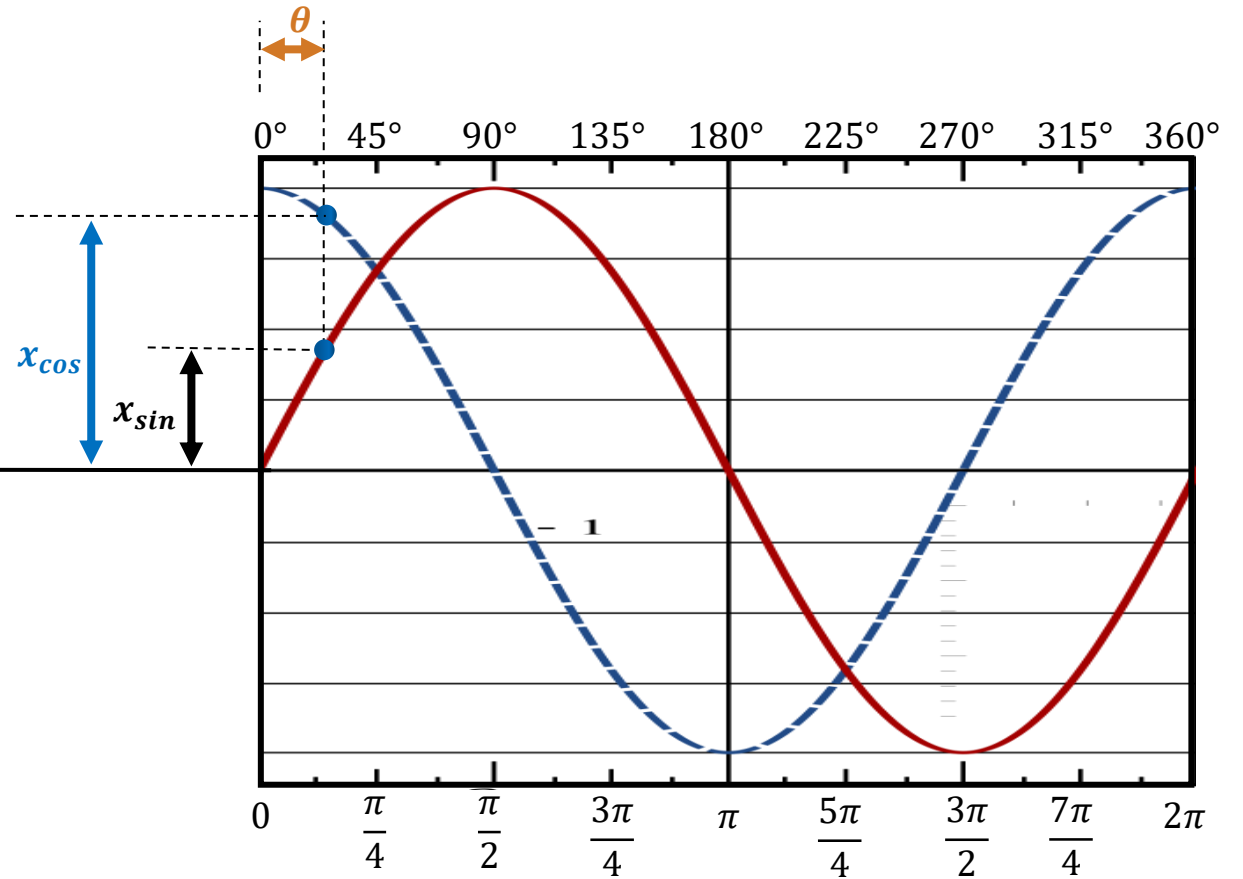
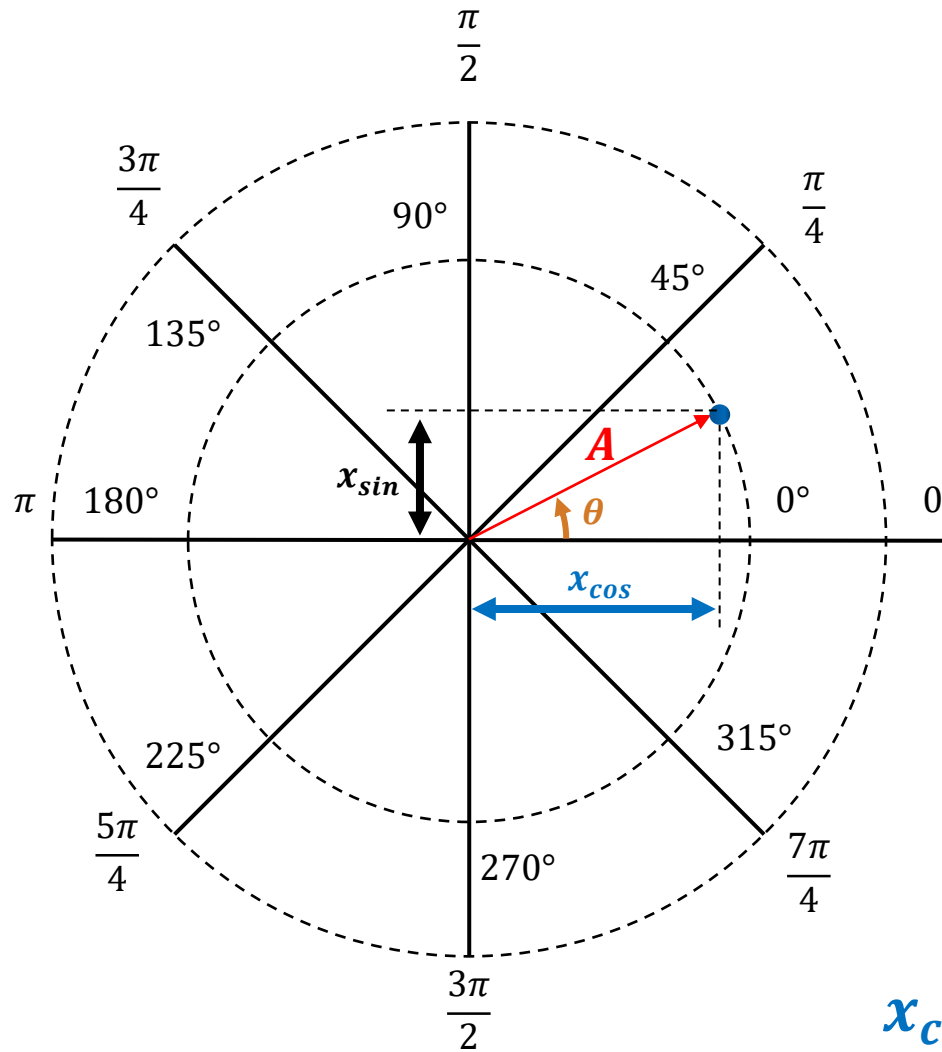


# Sinusoid – Phase Angle





# Sinusoid – Phase Angle

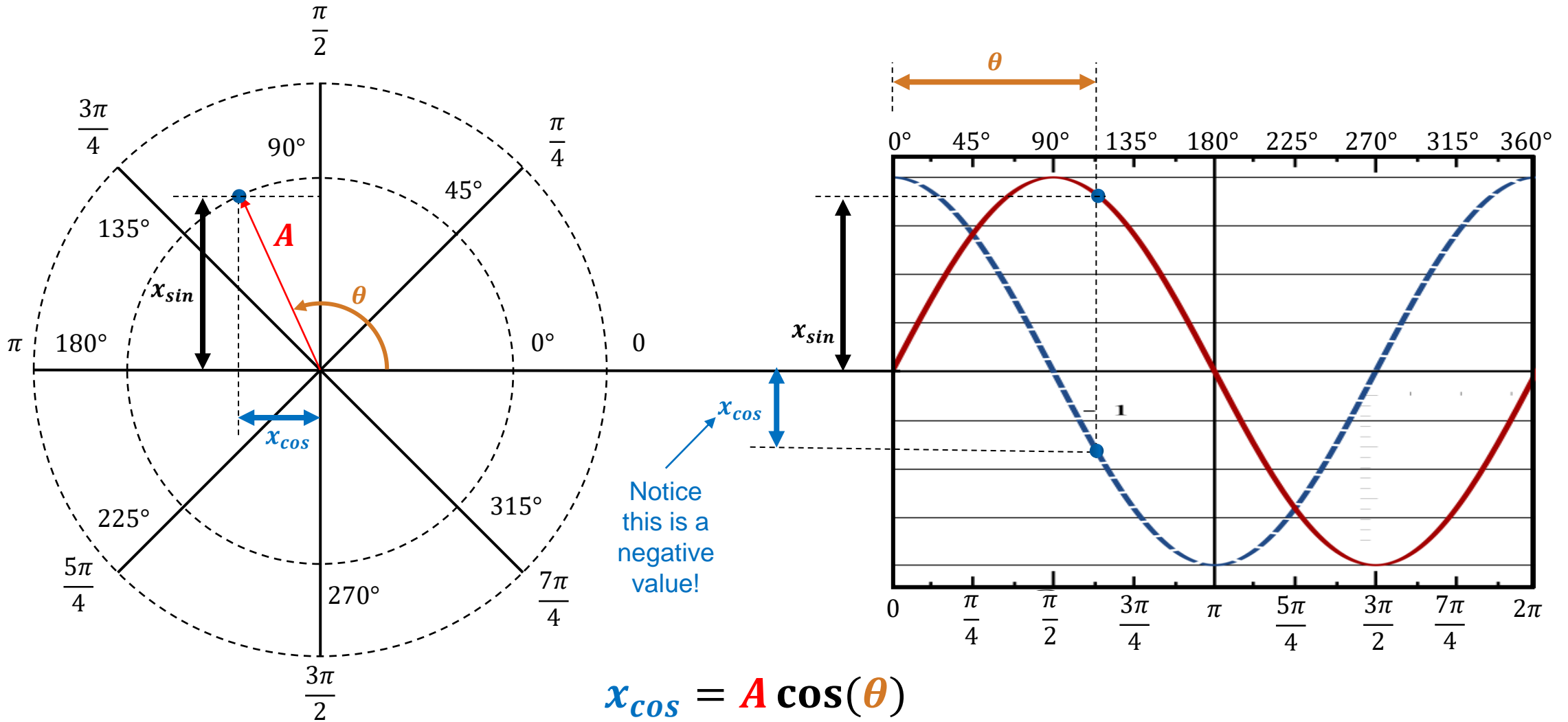


$$x_{cos} = A \cos(\theta)$$

$$x_{sin} = A \sin(\theta)$$



# Sinusoid – Phase Angle

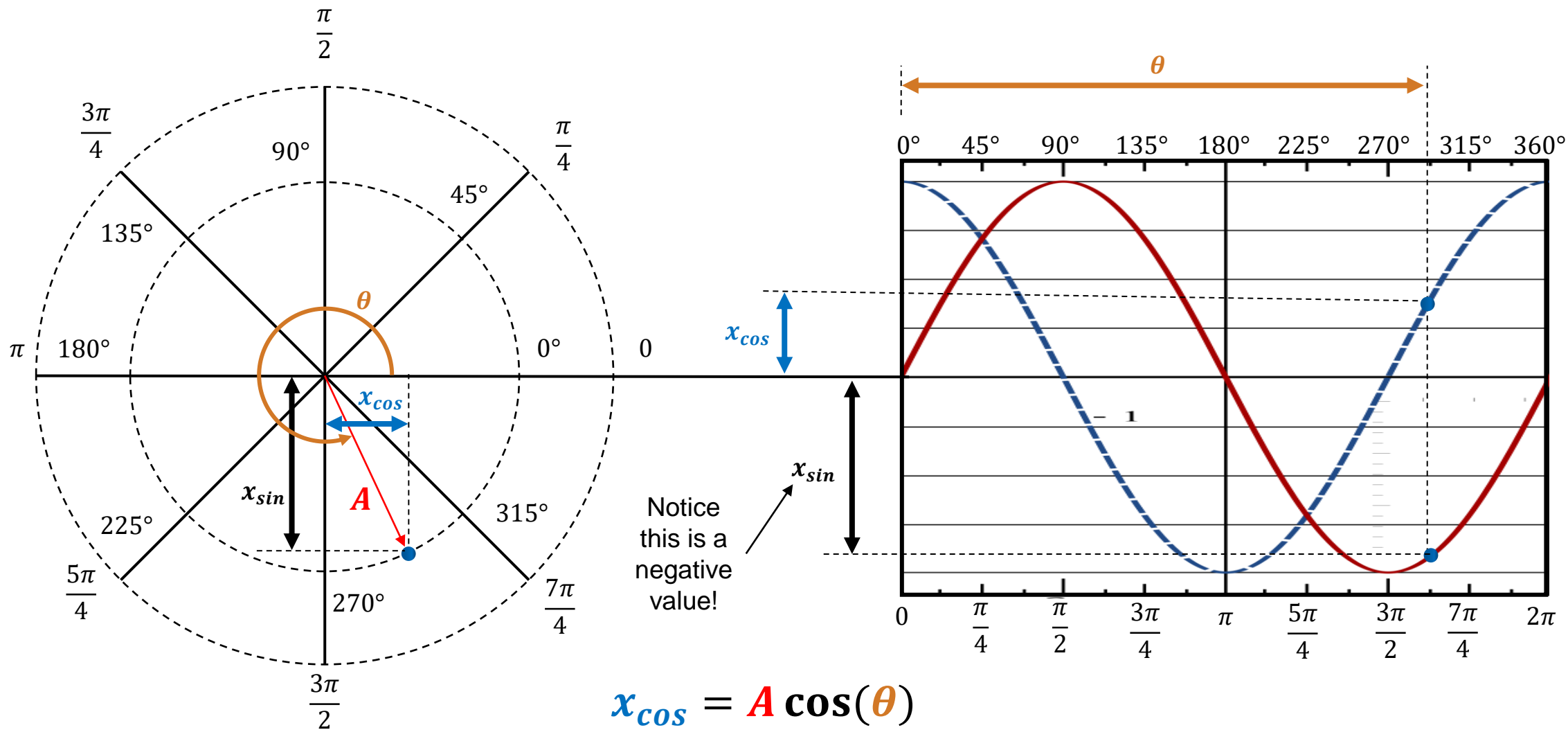


$$x_{cos} = A \cos(\theta)$$

$$x_{sin} = A \sin(\theta)$$



# Sinusoid – Phase Angle

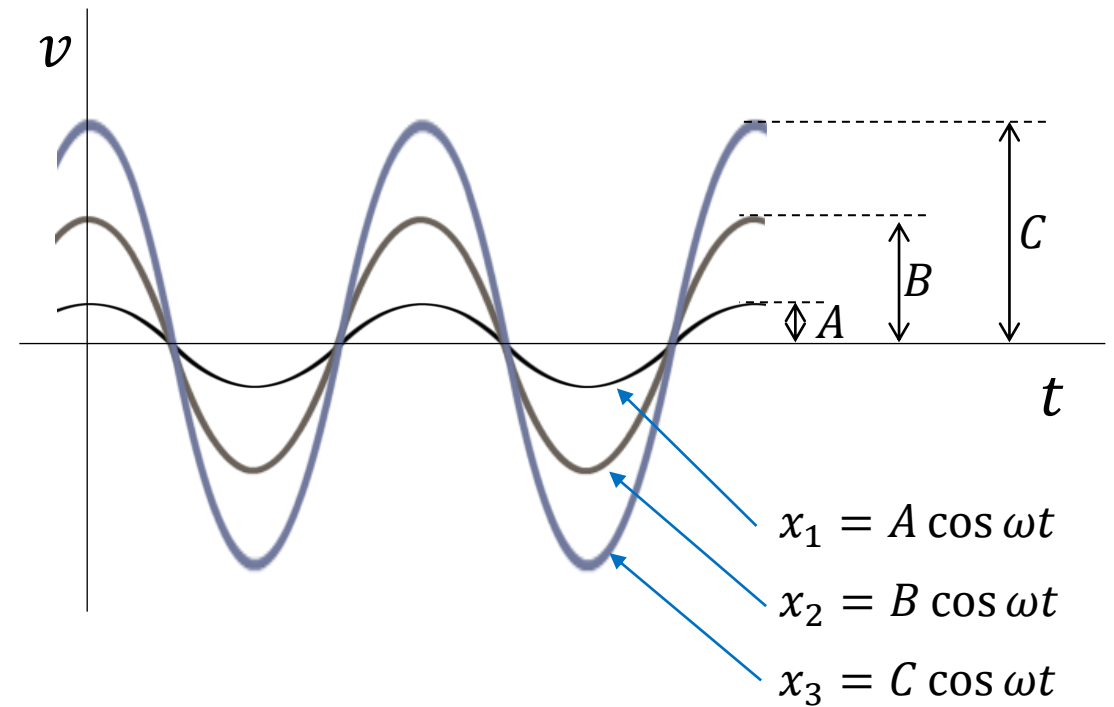
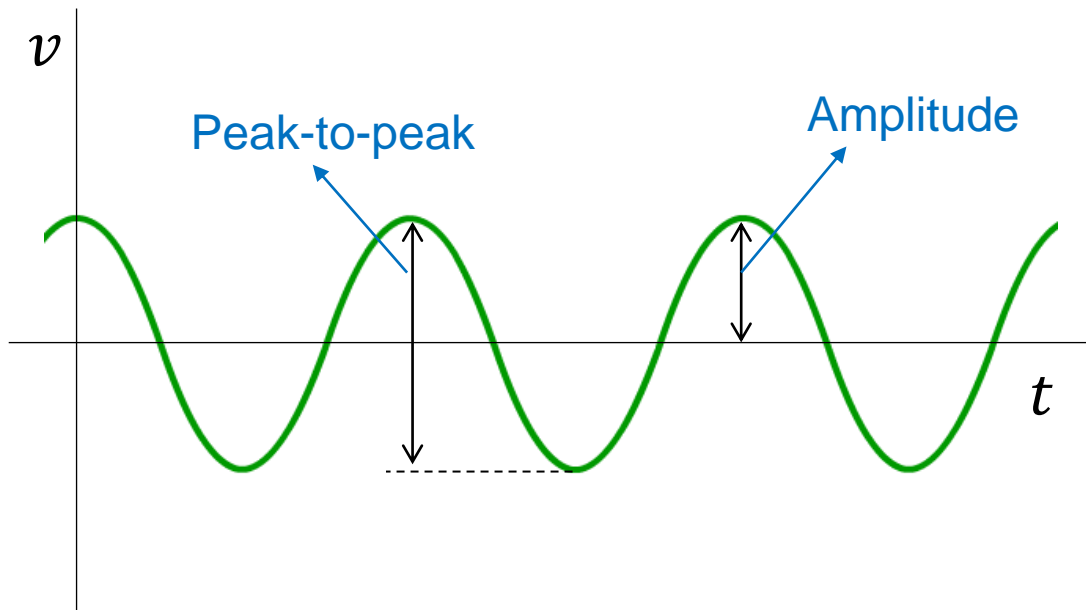


Notice this is a negative value!

$$x_{cos} = A \cos(\theta)$$

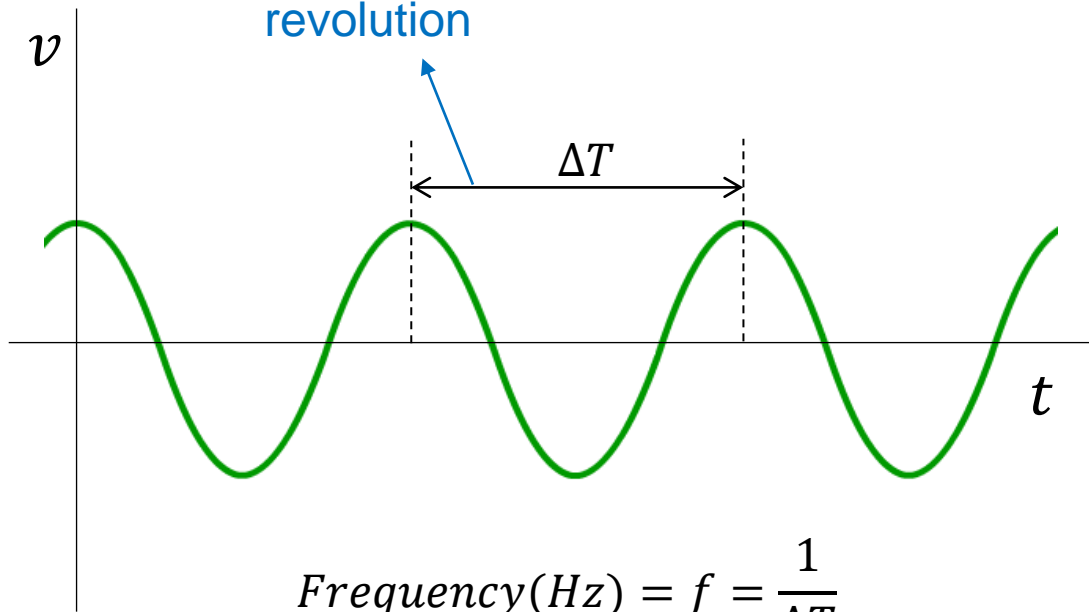
$$x_{sin} = A \sin(\theta)$$

## Maximum magnitude of the variable



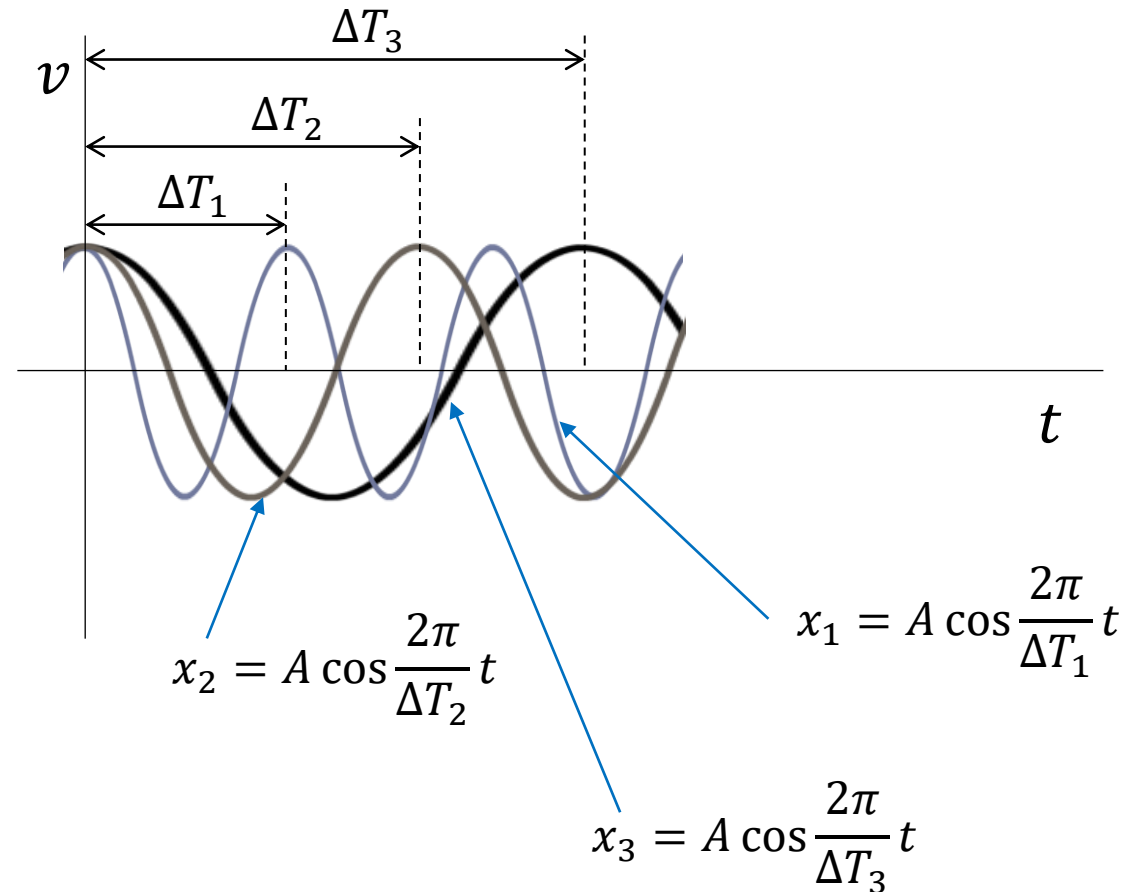
Indicates how fast is the variable changing

Time taken (in s) to perform one period, or revolution



$$\text{Frequency (Hz)} = f = \frac{1}{\Delta T}$$

$$\text{Angular Speed} \left( \frac{\text{rad}}{\text{s}} \right) = \omega = 2\pi f = \frac{2\pi}{\Delta T}$$

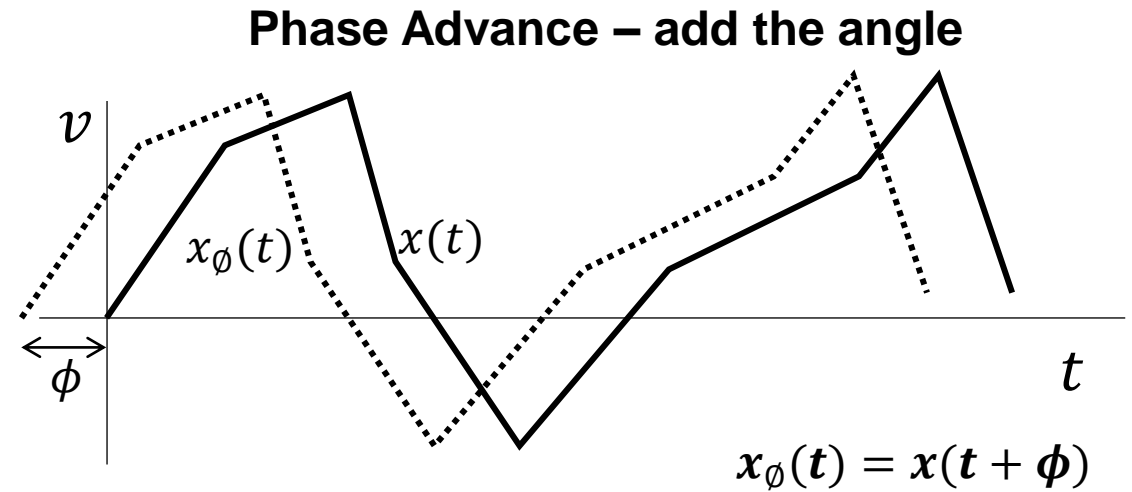
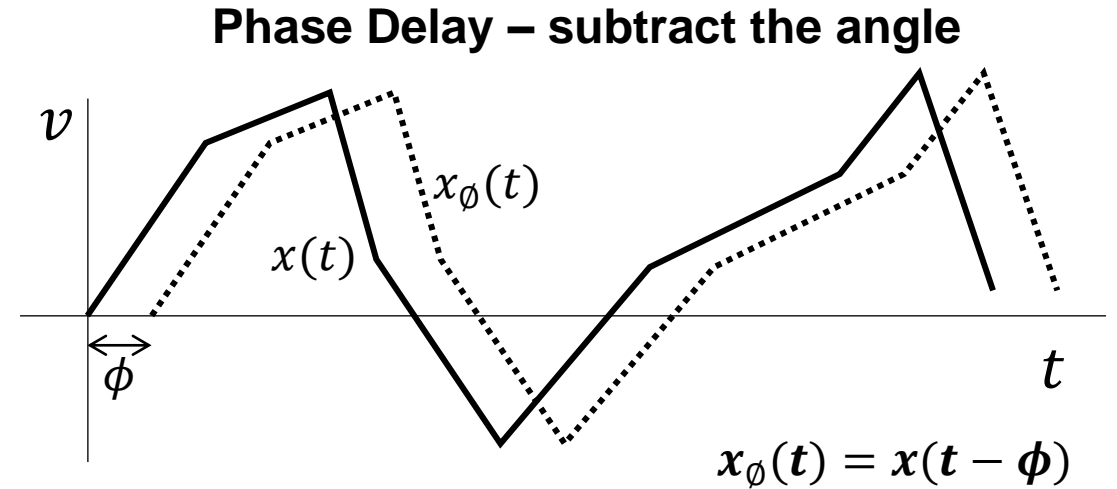
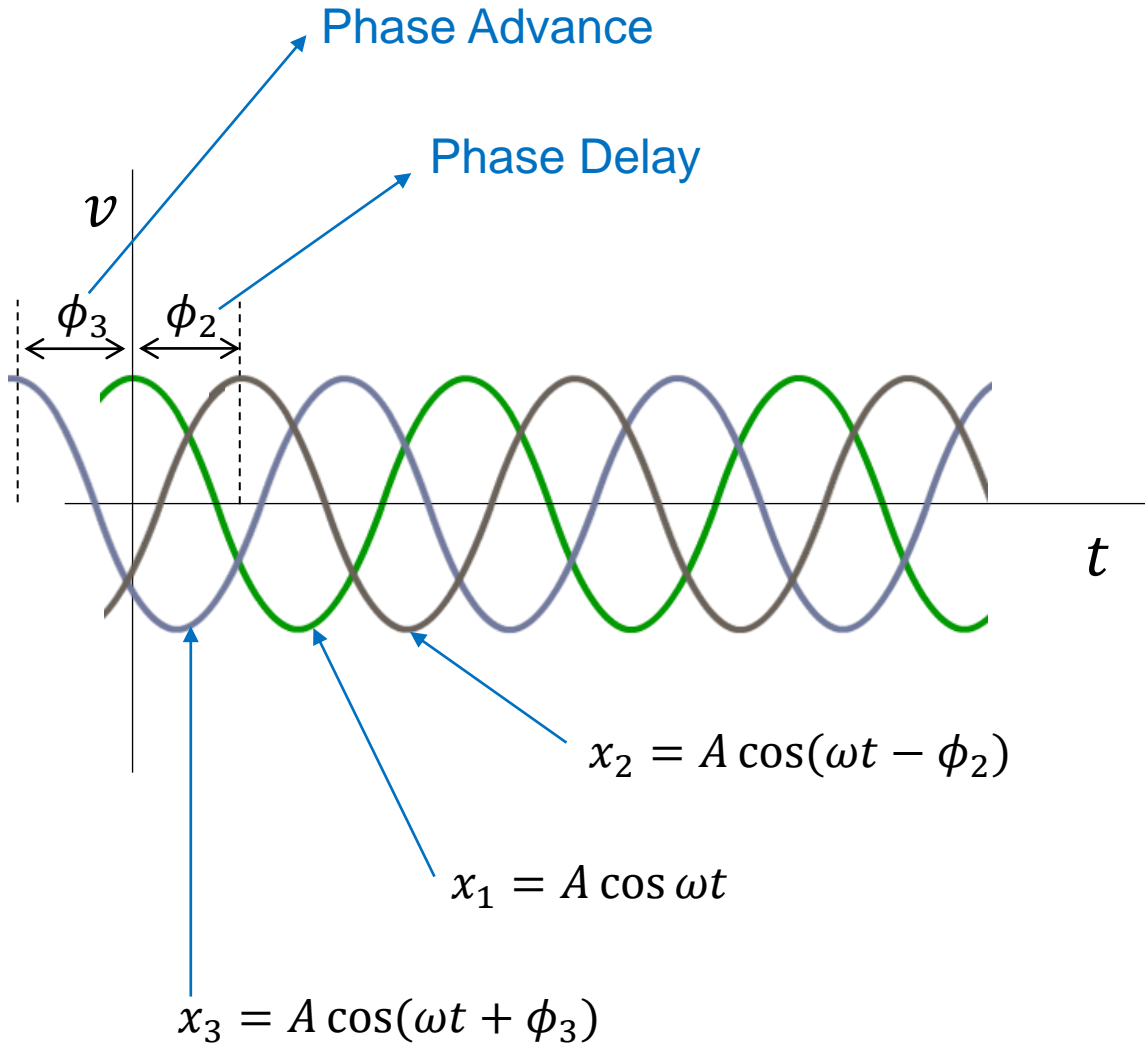


$$x_2 = A \cos \frac{2\pi}{\Delta T_2} t$$

$$x_1 = A \cos \frac{2\pi}{\Delta T_1} t$$

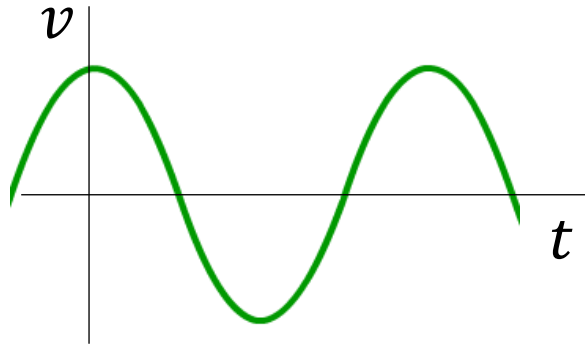
$$x_3 = A \cos \frac{2\pi}{\Delta T_3} t$$

## Phase angle at $t = 0$



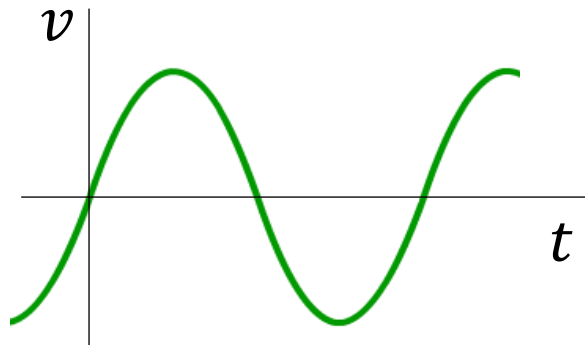


# Sinusoid – Phase Offset



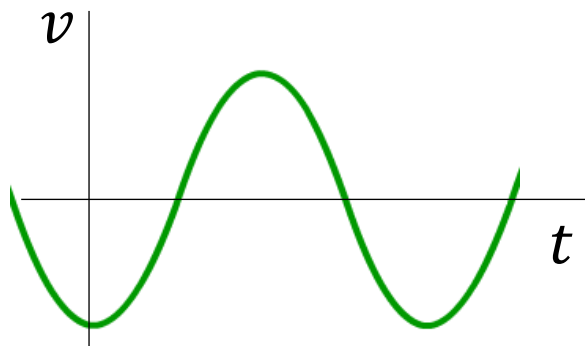
$$x_1 = A \cos \omega t$$

Add a Phase Delay of  $\frac{\pi}{2}$



$$x_2 = A \cos\left(\omega t - \frac{\pi}{2}\right) = A \sin \omega t$$

Add a Phase Delay of  $\frac{\pi}{2}$



$$x_3 = A \sin\left(\omega t - \frac{\pi}{2}\right) = -A \cos \omega t$$

$$x_6 = -A \sin\left(\omega t + \frac{\pi}{2}\right) = -A \cos \omega t$$



Add a Phase Advance of  $\frac{\pi}{2}$

$$x_5 = A \cos\left(\omega t + \frac{\pi}{2}\right) = -A \sin \omega t$$



Add a Phase Advance of  $\frac{\pi}{2}$

$$x_4 = A \cos \omega t$$

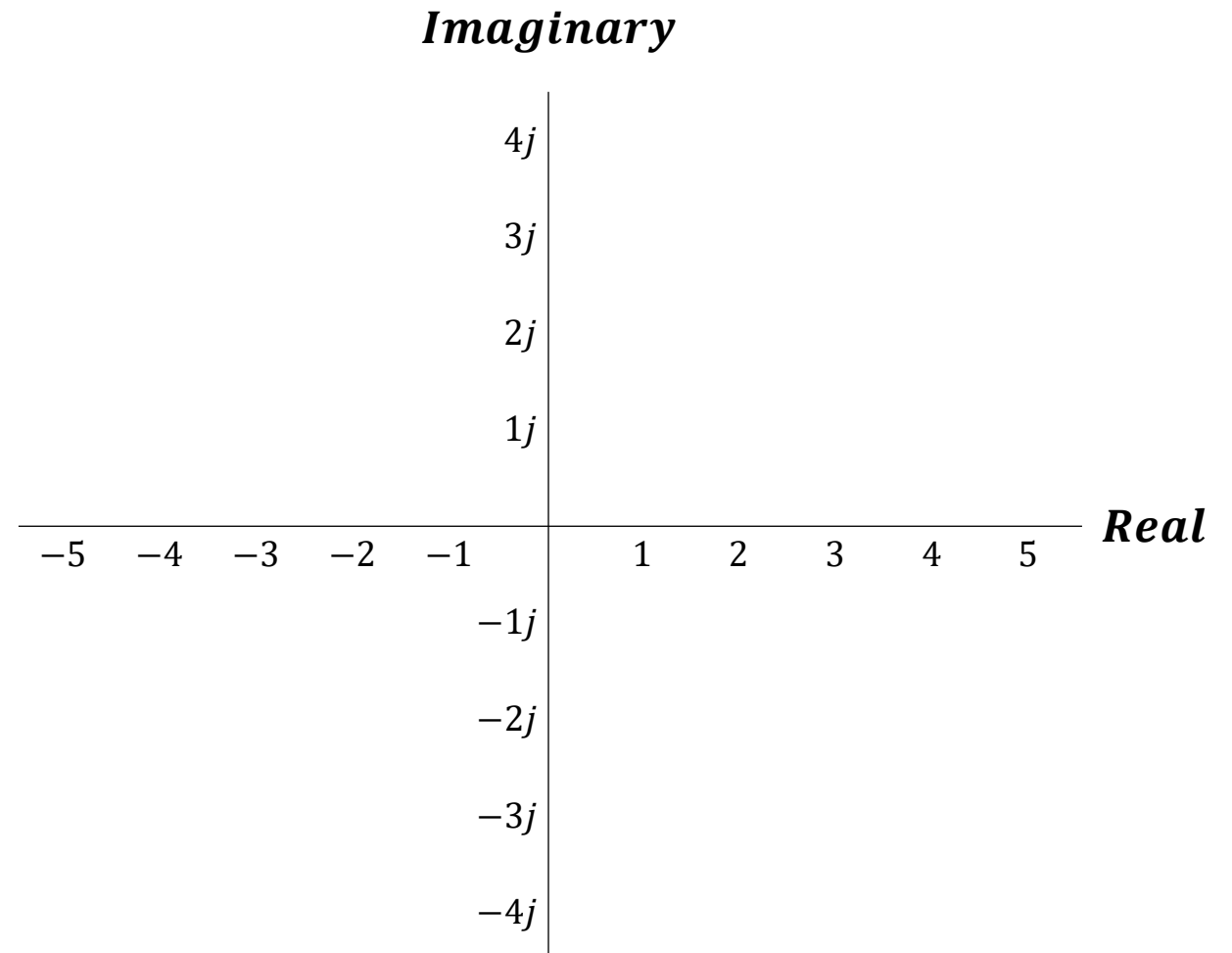


## Solution of $x^2 = -1$

$$x = \sqrt{-1}$$

$$x = j$$

**Argand Plane**, or complex plane is used to represent complex numbers in the cartesian coordinate system



**Cartesian Form** – Use the x & y coordinates to represent the complex number

$$4 + j3$$

$$x + jy \text{ (general form)}$$

**Polar Form** – Use the magnitude & angle to represent the complex number

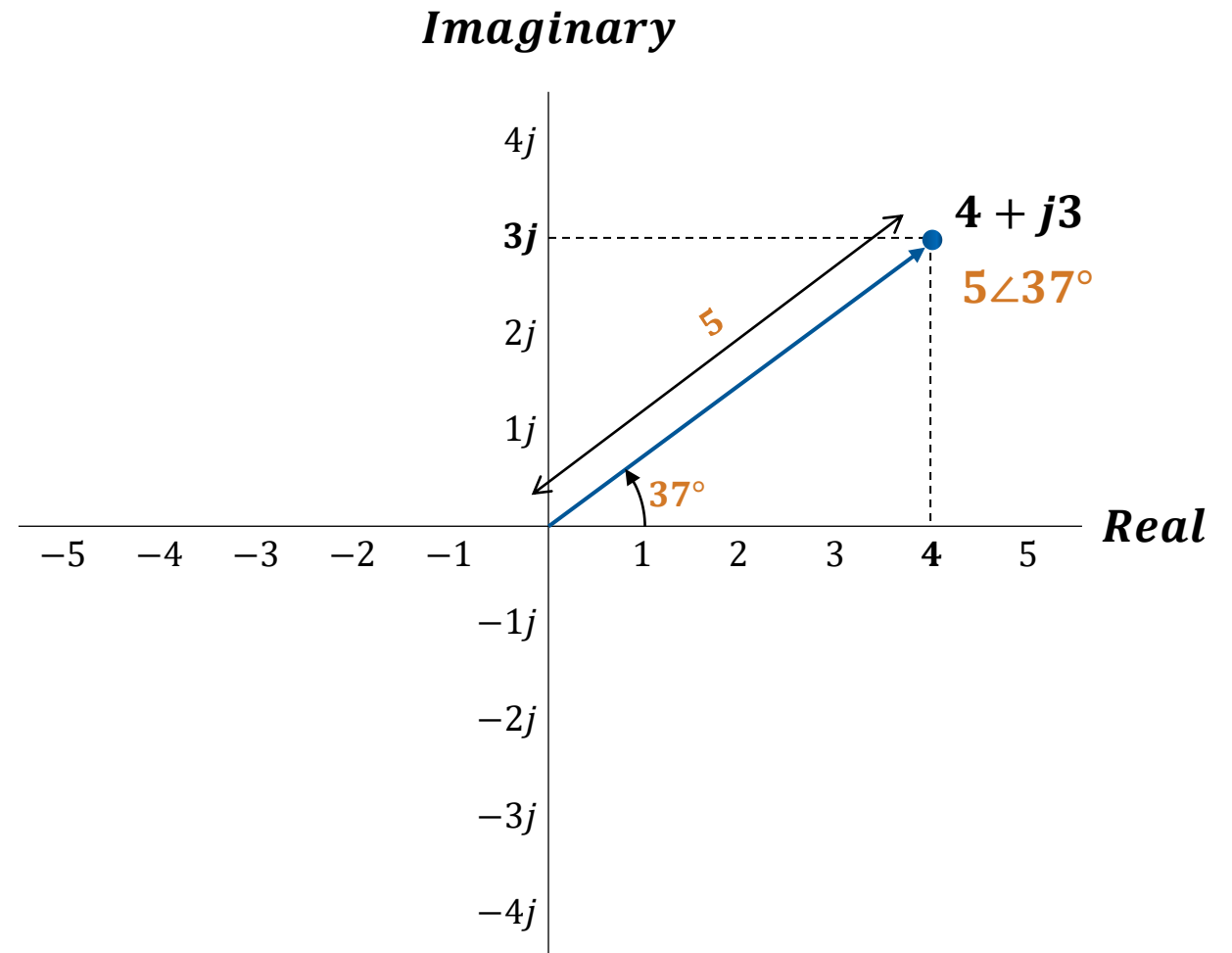
$$5 \angle 37^\circ$$

$$|V| \angle \theta \text{ (general form)}$$

**Exponential Form** – Variation of Polar Form

$$5e^{j37^\circ}$$

$$|V|e^{j\theta} \text{ (general form)}$$





## Cartesian to Polar Conversion

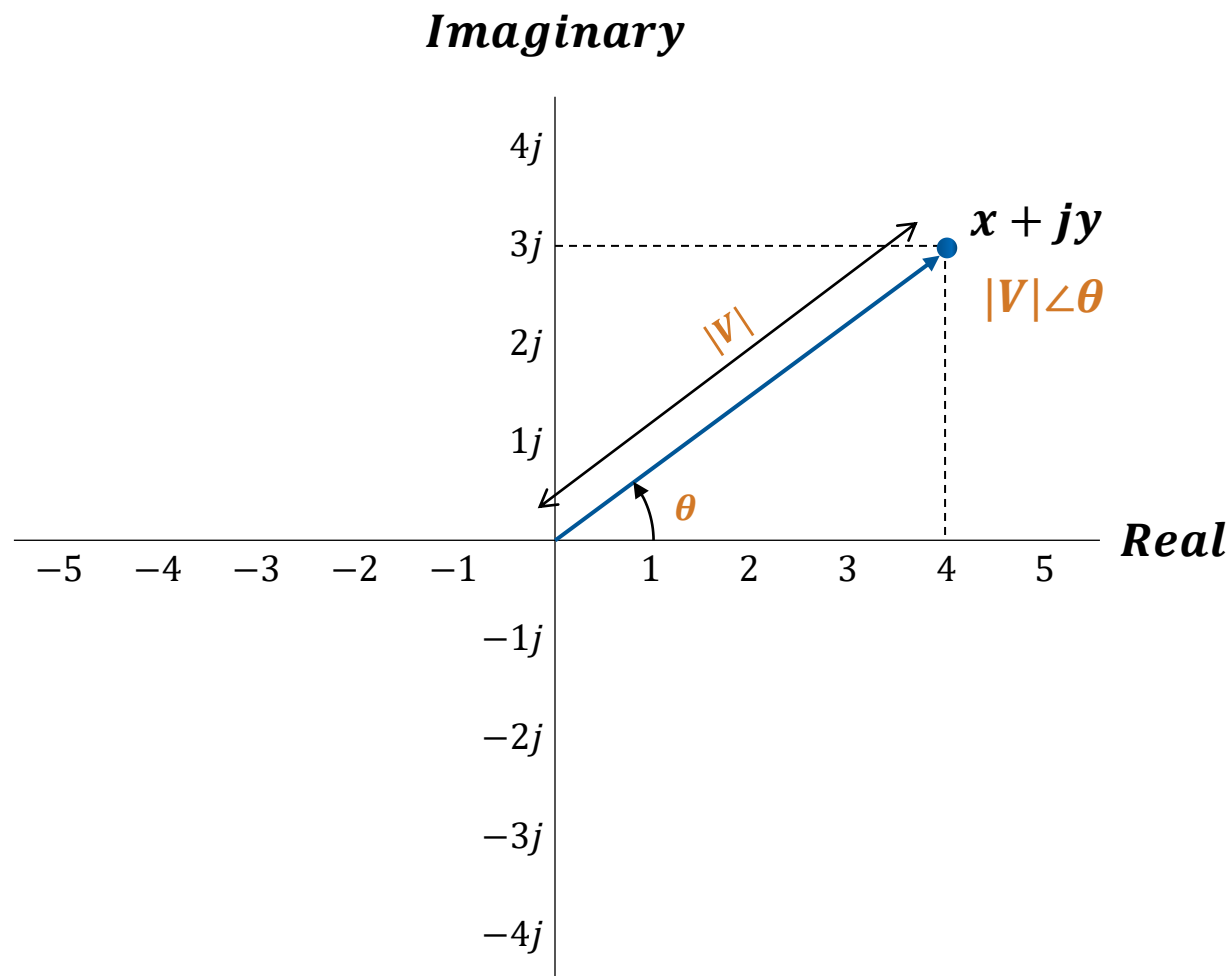
$$|V| = \sqrt{x^2 + y^2}$$

$$\theta = \tan^{-1} \frac{y}{x}$$

## Polar to Cartesian Conversion

$$x = |V| \cos \theta$$

$$y = |V| \sin \theta$$

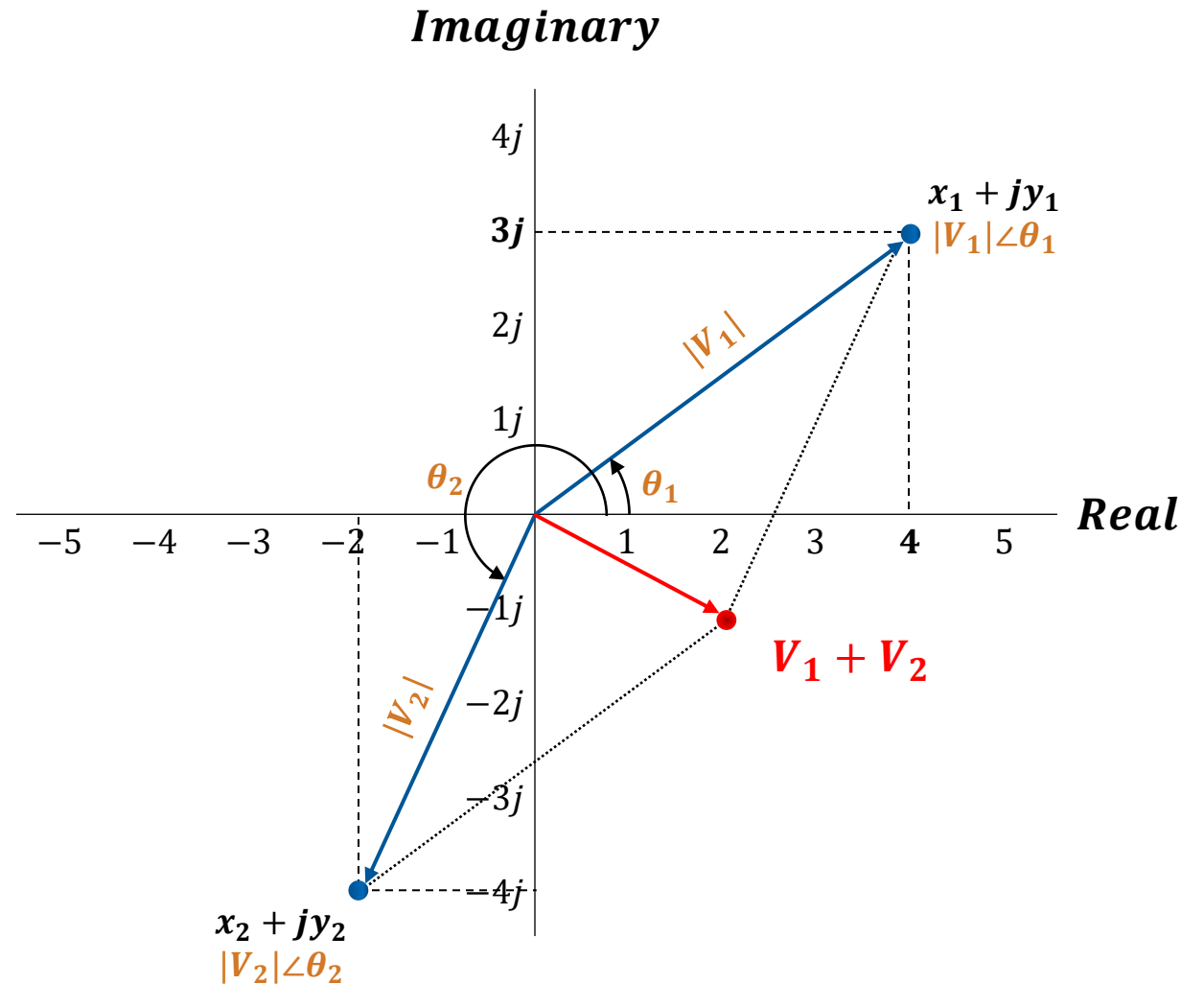


## Addition

$$V_1 + V_2 = (x_1 + jy_1) + (x_2 + jy_2)$$

$$V_1 + V_2 = (x_1 + x_2) + j(y_1 + y_2)$$

*Simply add the real terms and imaginary terms separately*



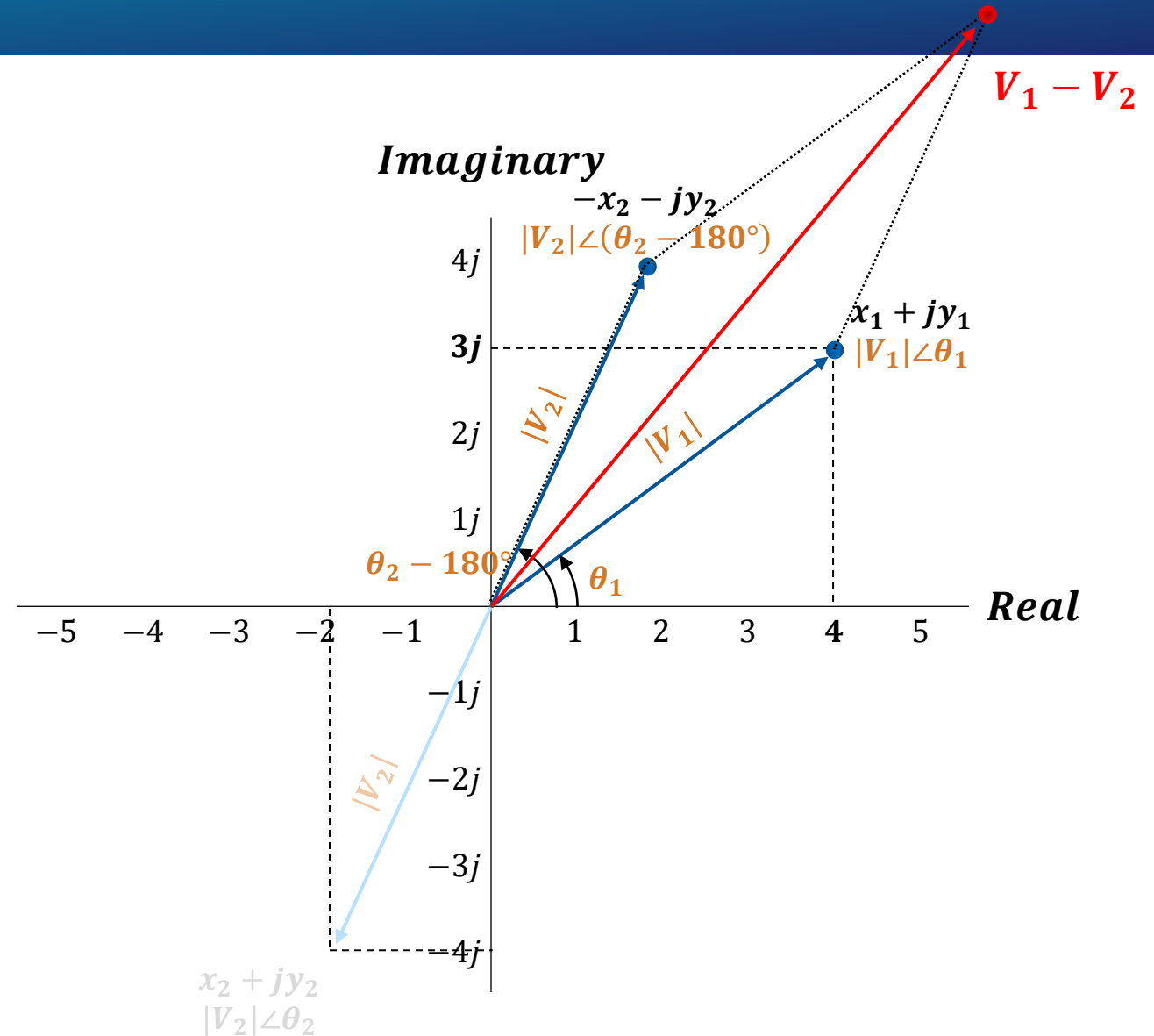


## Subtraction

$$V_1 - V_2 = (x_1 + jy_1) - (x_2 + jy_2)$$

$$V_1 - V_2 = (x_1 - x_2) + j(y_1 - y_2)$$

Simply subtract the real terms and imaginary terms separately



## Multiplication

$$V_1 \times V_2 = (x_1 + y_1j) \times (x_2 + y_2j)$$

$$V_1 \times V_2 = x_1x_2 + x_1y_2j + y_1x_2 + y_1y_2j^2$$

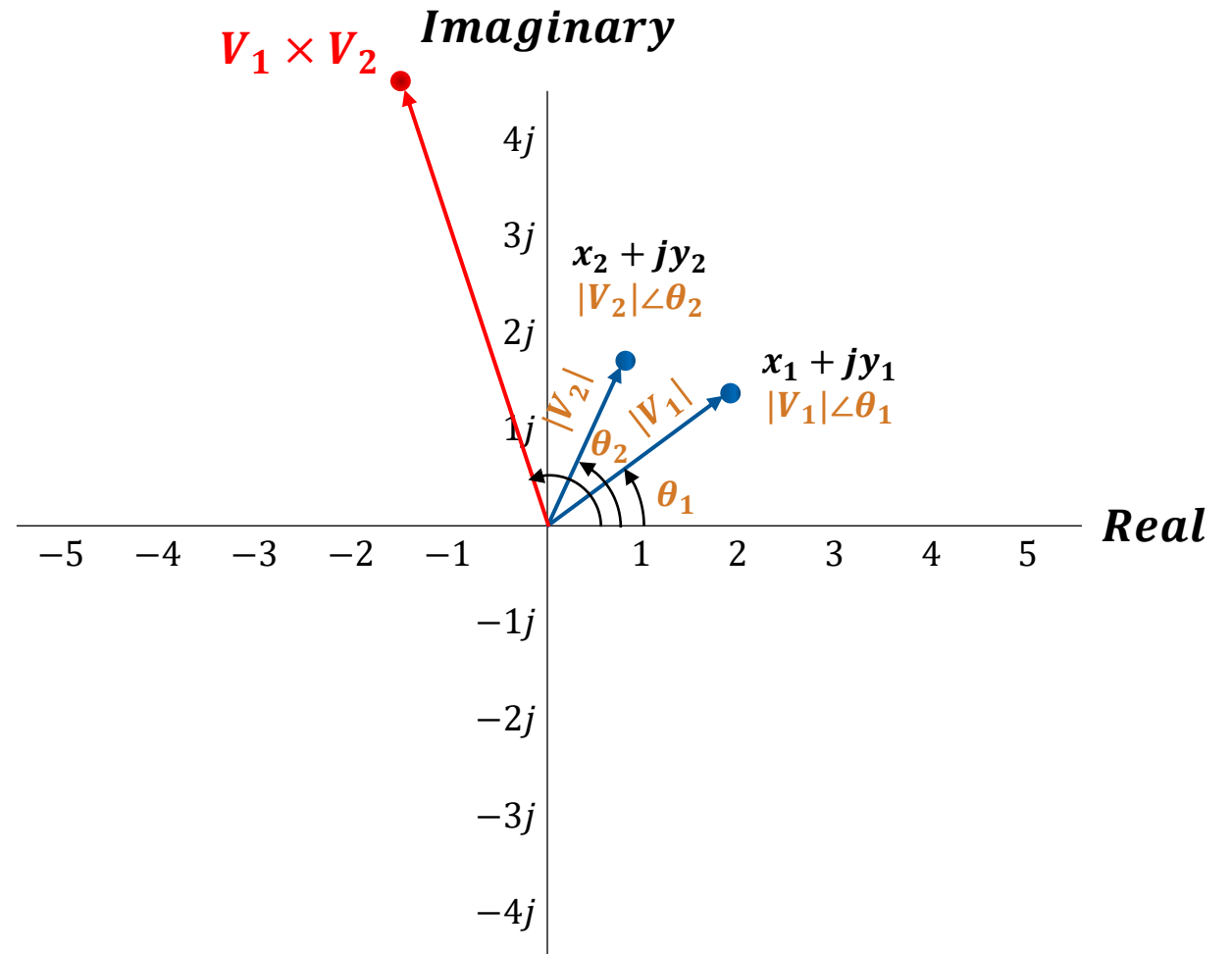
$$V_1 \times V_2 = x_1x_2 + x_1y_2j + y_1x_2j + y_1y_2(-1)$$

$$V_1 \times V_2 = (x_1x_2 - y_1y_2) + (x_1y_2 + y_1x_2)j$$

### *Simpler method using Polar Form*

$$V_1 \times V_2 = |V_1| |V_2| \angle(\theta_1 + \theta_2) V_1 \times V_2$$

$$= |V_1| \angle\theta_1 \times |V_2| \angle\theta_2$$





## Division

$$V_1 \div V_2 = \frac{(x_1 + jy_1)}{(x_2 + jy_2)}$$

$$V_1 \div V_2 = \frac{(x_1 + jy_1) \times (x_2 - jy_2)}{(x_2 + jy_2) \times (x_2 - jy_2)}$$

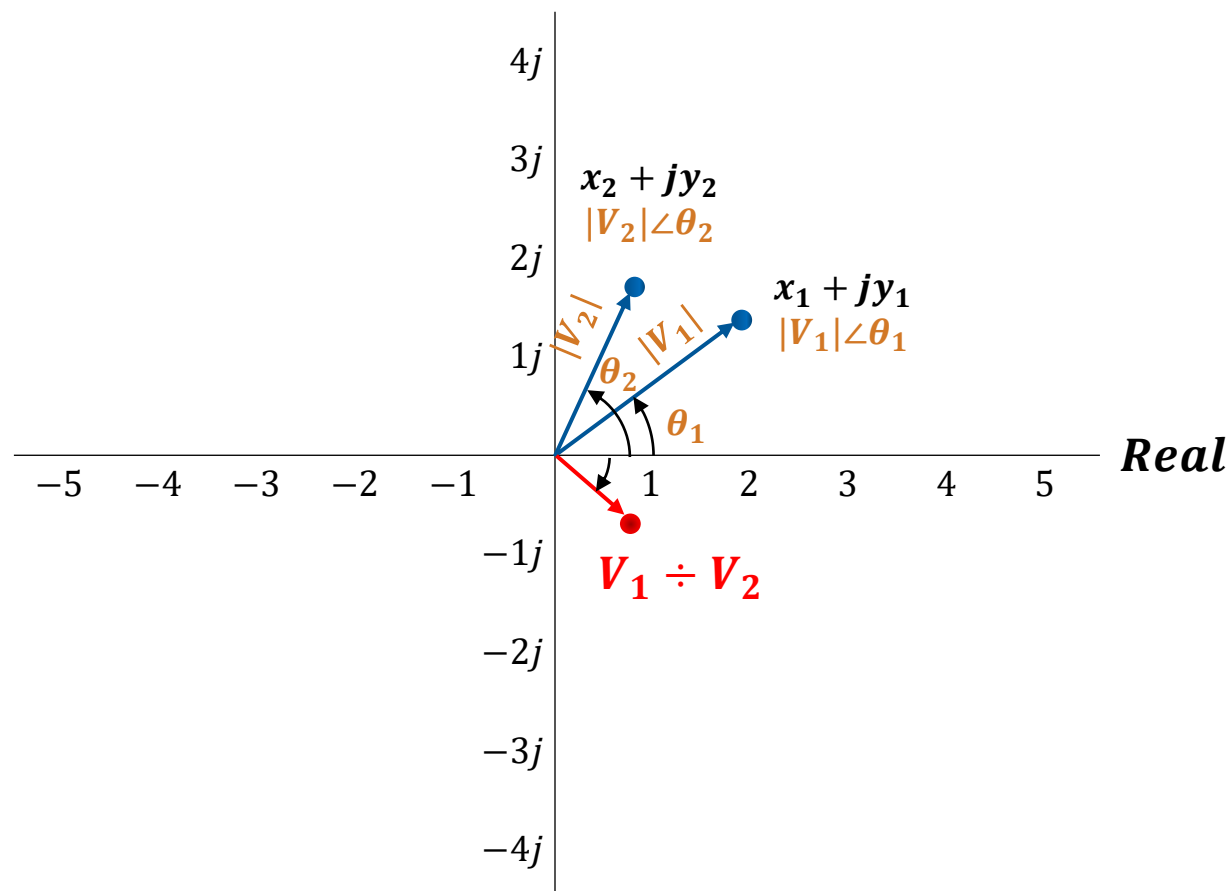
$$V_1 \div V_2 = \frac{(x_1x_2 + y_1y_2) - j(x_1y_2 - y_1x_2)}{(x_2^2 - y_2^2)}$$

## Simpler method using Polar Form

$$V_1 \div V_2 = |V_1| \angle \theta_1 \div |V_2| \angle \theta_2$$

$$V_1 \div V_2 = \frac{|V_1|}{|V_2|} \angle (\theta_1 - \theta_2)$$

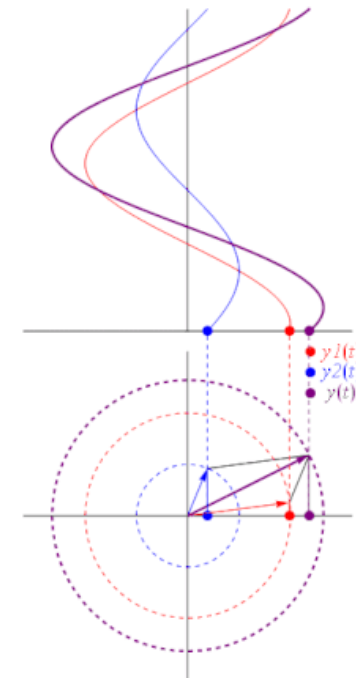
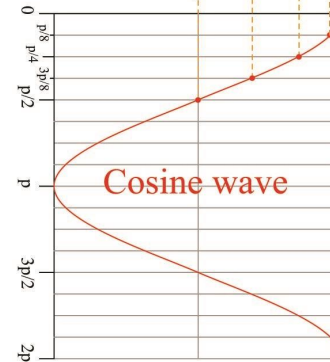
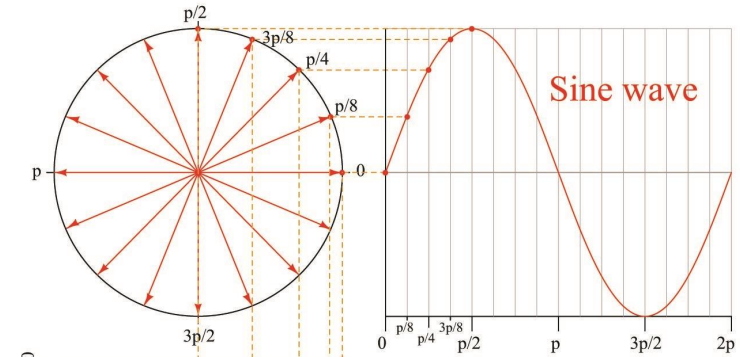
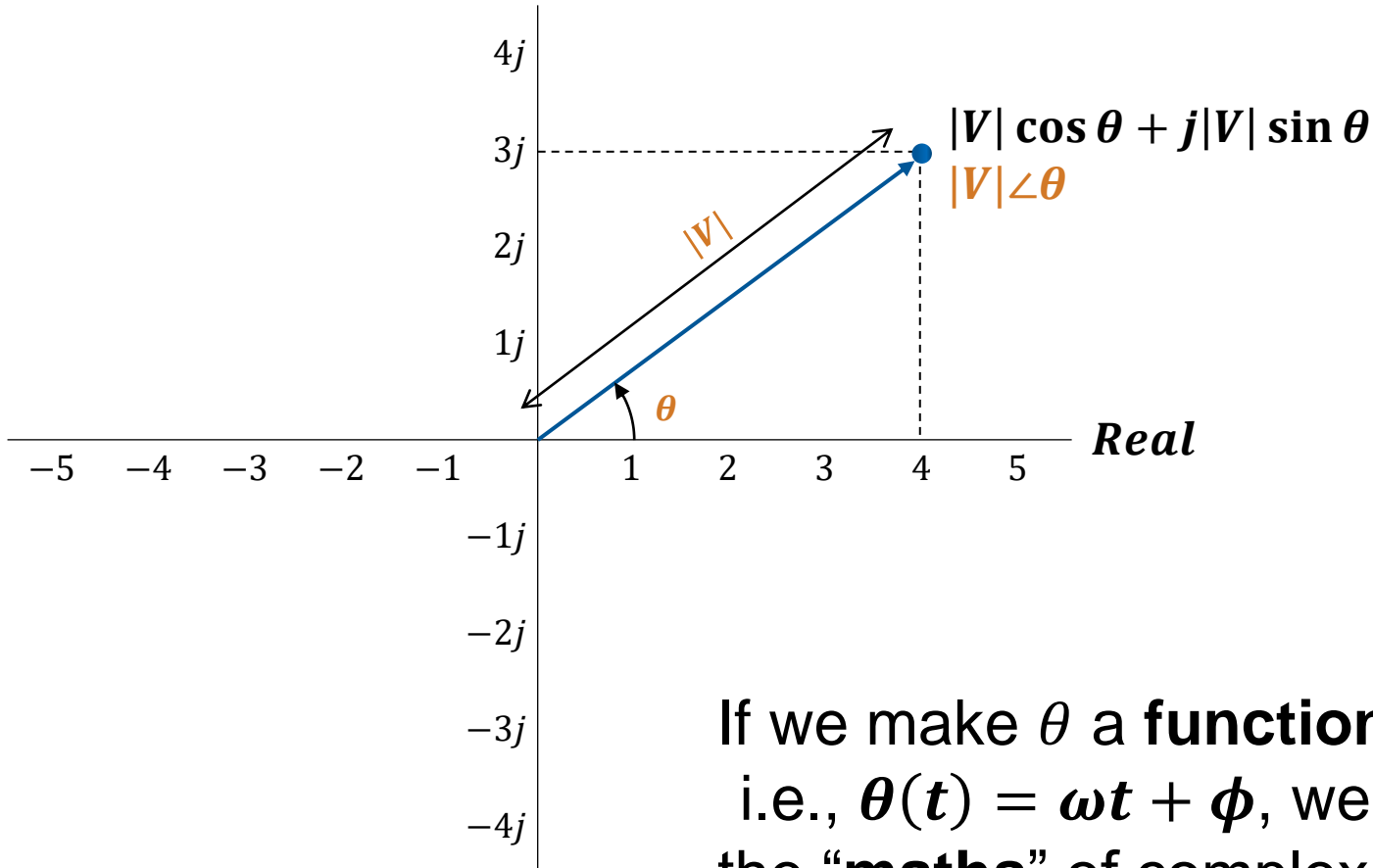
## Imaginary





- Fundamentals of **Alternating Current – or AC**
  - DC v AC circuit study – waveforms a **function of time!**
  - **Sinusoidal** waveform – voltage & current
  - **Complex Numbers**
- AC circuits
  - **Phasor** study – simple way to solve time-varying circuits
  - Resistor, Inductor, Capacitor in phasor form - **CIVIL**
  - **Reactance** – Purely reactive circuits (just inductor/capacitor)
  - **Impedance** – Resistance & Reactance
- Power in AC circuits
  - **Active v Reactive v Apparent Power**
  - **Power Factor**
  - **Resonance**

*Imaginary*

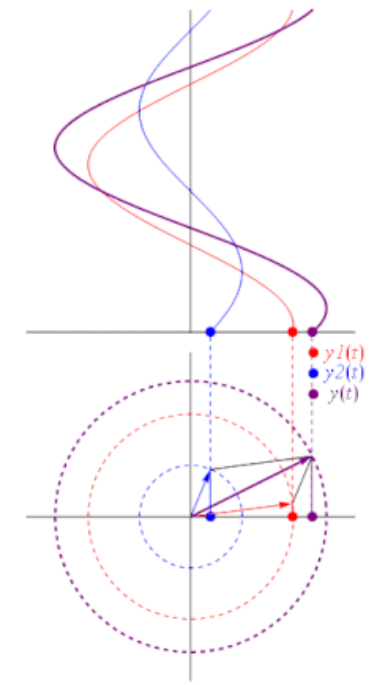
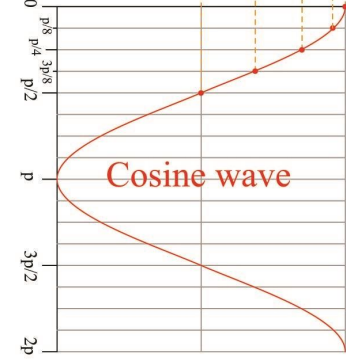
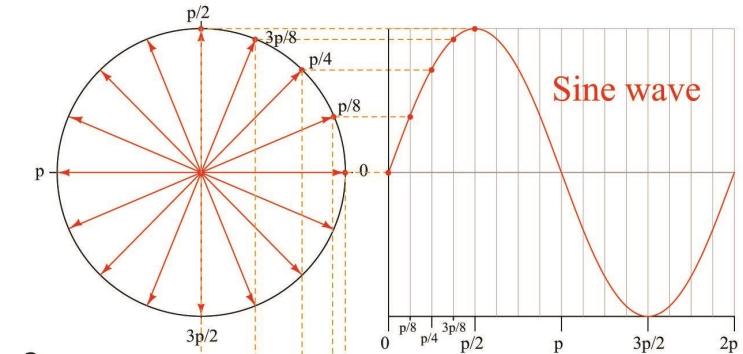
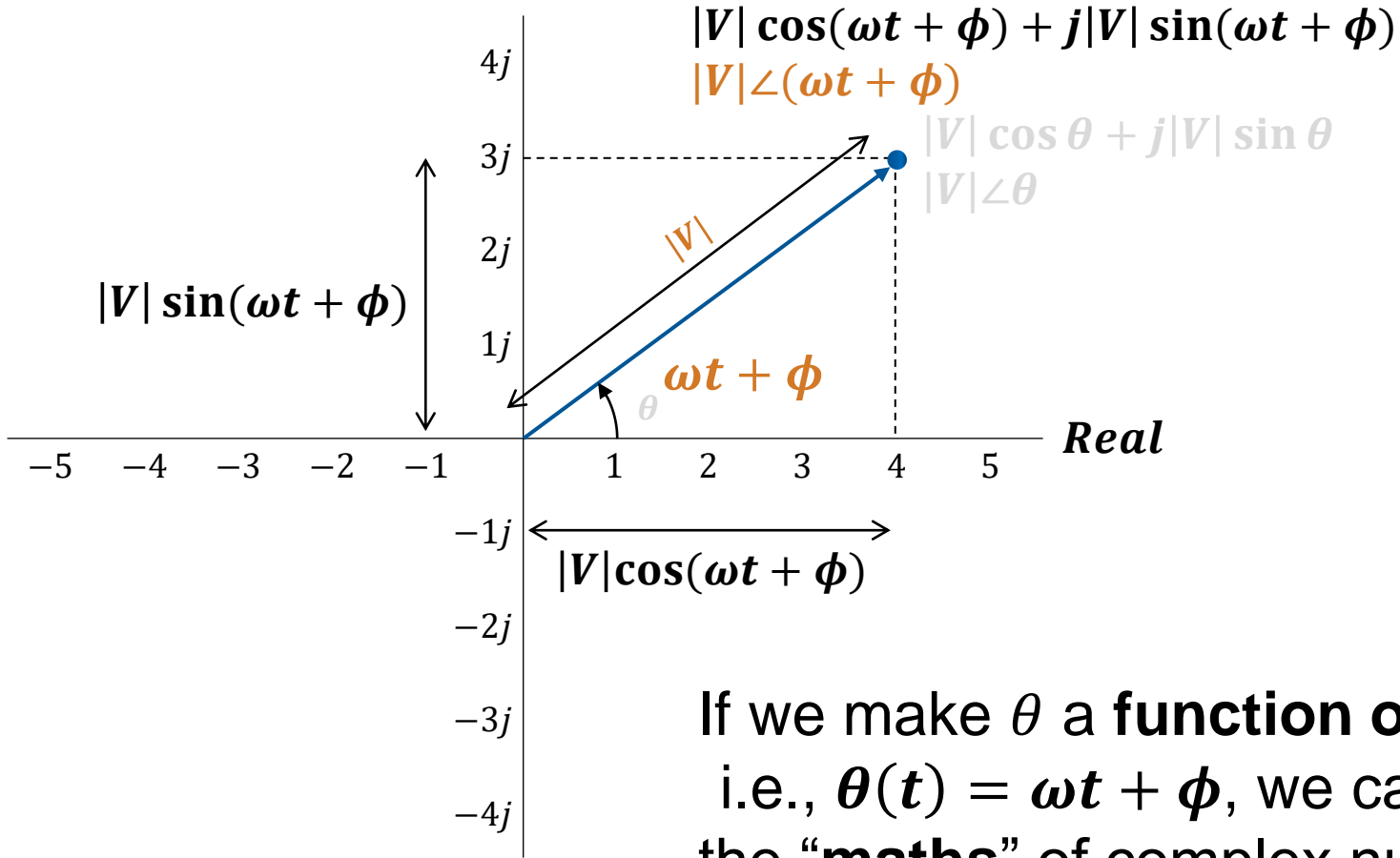


If we make  $\theta$  a function of time, i.e.,  $\theta(t) = \omega t + \phi$ , we can use the “**maths**” of complex numbers to do the “**electrical**” of AC!



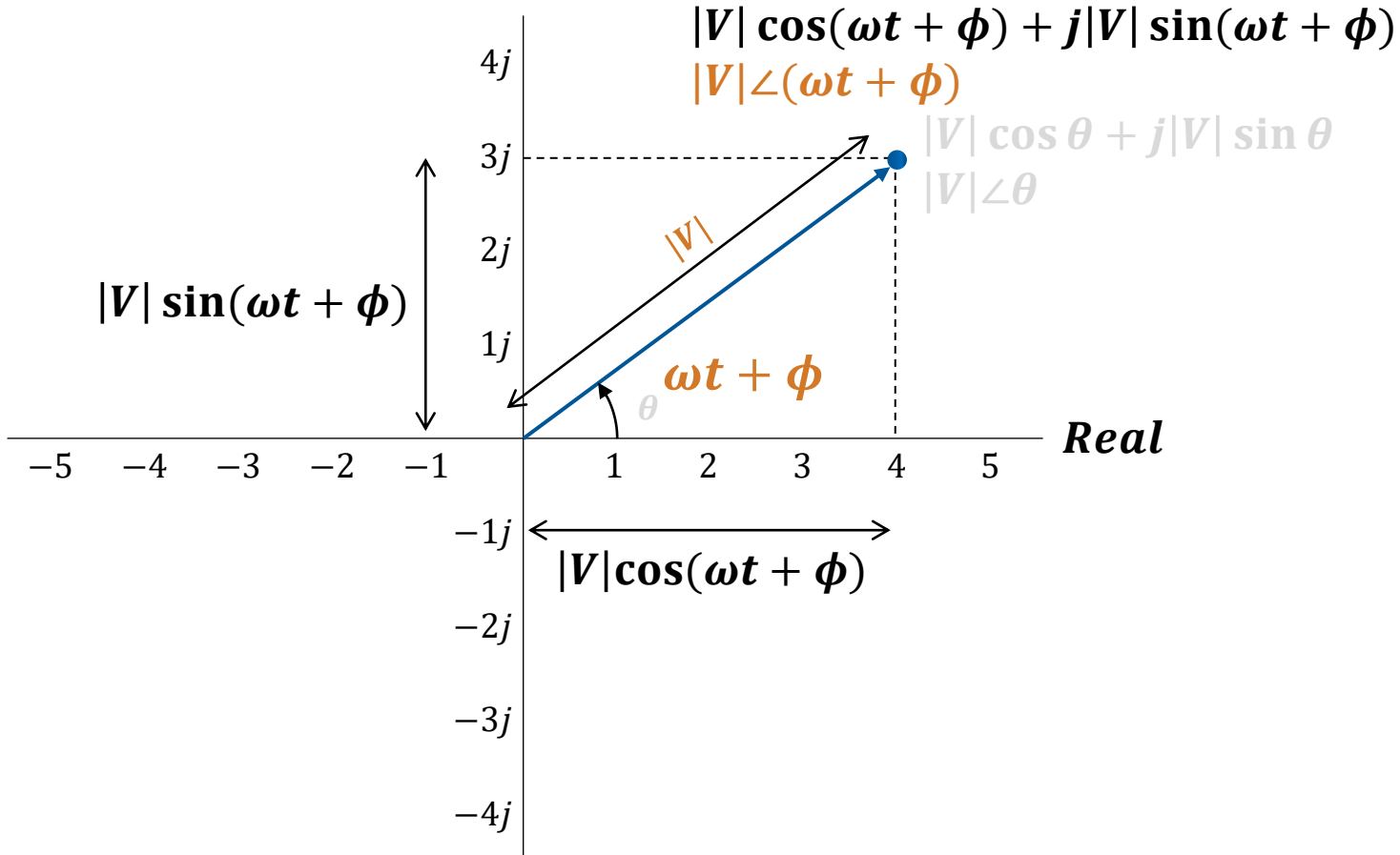
# Phasor

*Imaginary*



If we make  $\theta$  a function of time, i.e.,  $\theta(t) = \omega t + \phi$ , we can use the “**maths**” of complex numbers to do the “**electrical**” of AC!

*Imaginary*

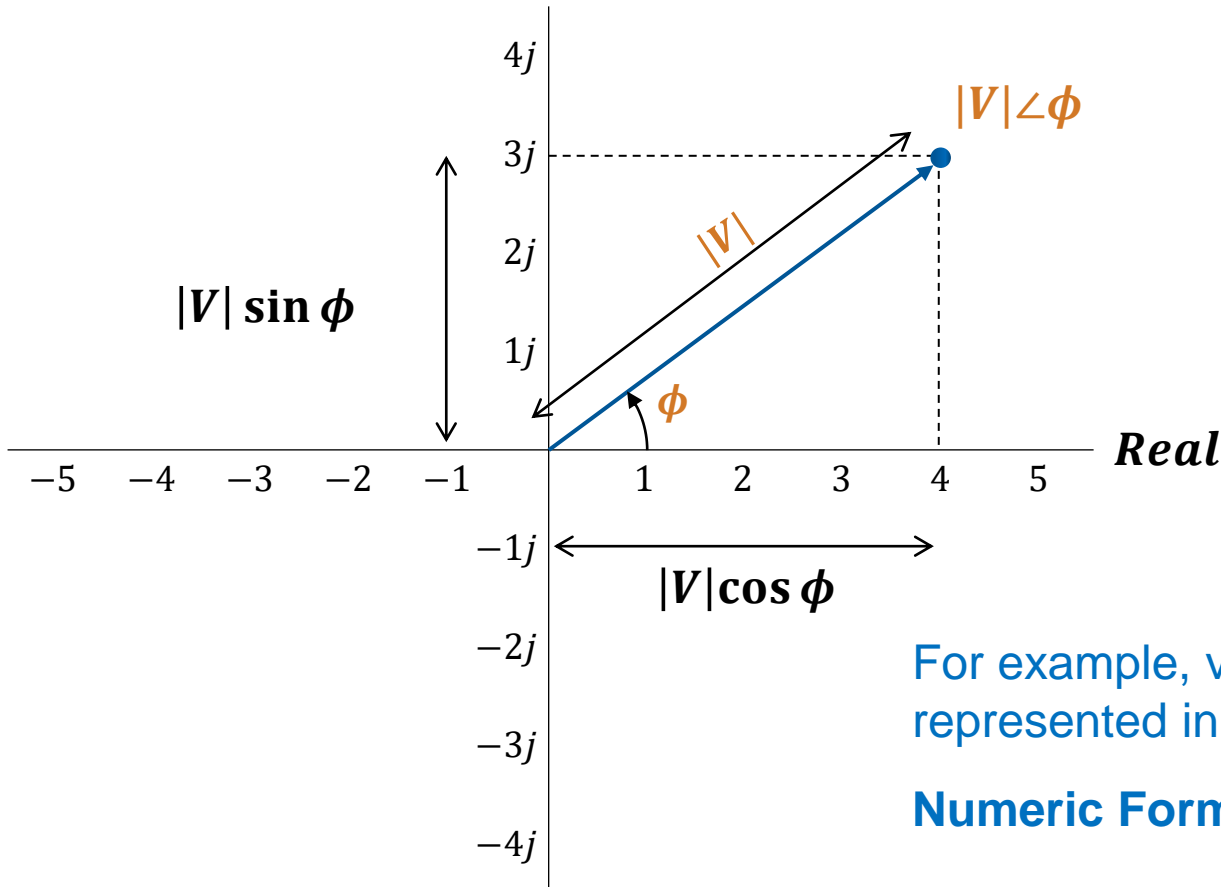


Say we have a voltage variable  
 $v = |V| \cos(\omega t + \phi)$

We may represent it with a “phasor” which is nothing but a complex number that represents the initial position of the rotating vector (i.e., at  $t = 0$ ), and say the “projection on positive real axis” is the value of the physical variable

# Phasor

*Imaginary*

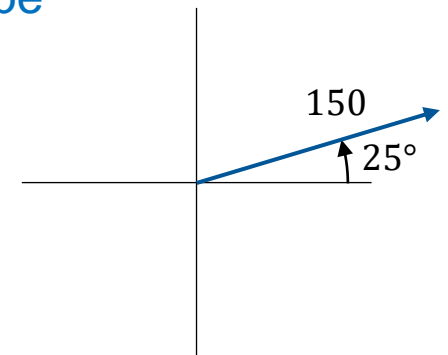


- A phasor is a complex number that represents the initial position of a rotating vector, i.e., at  $t = 0$
- Use the amplitude ( $|V|$ ) and phase offset ( $\phi$ ) of a cosine function
- For all AC steady-state analysis,  $|V|$  and  $\phi$  are all we need to get meaningful results
- AC steady-state analysis – this assumes frequency  $\omega$  does not change

For example, voltage  $v = 150 \cos(50t + 25^\circ)$  may be represented in the phasor form as follows:

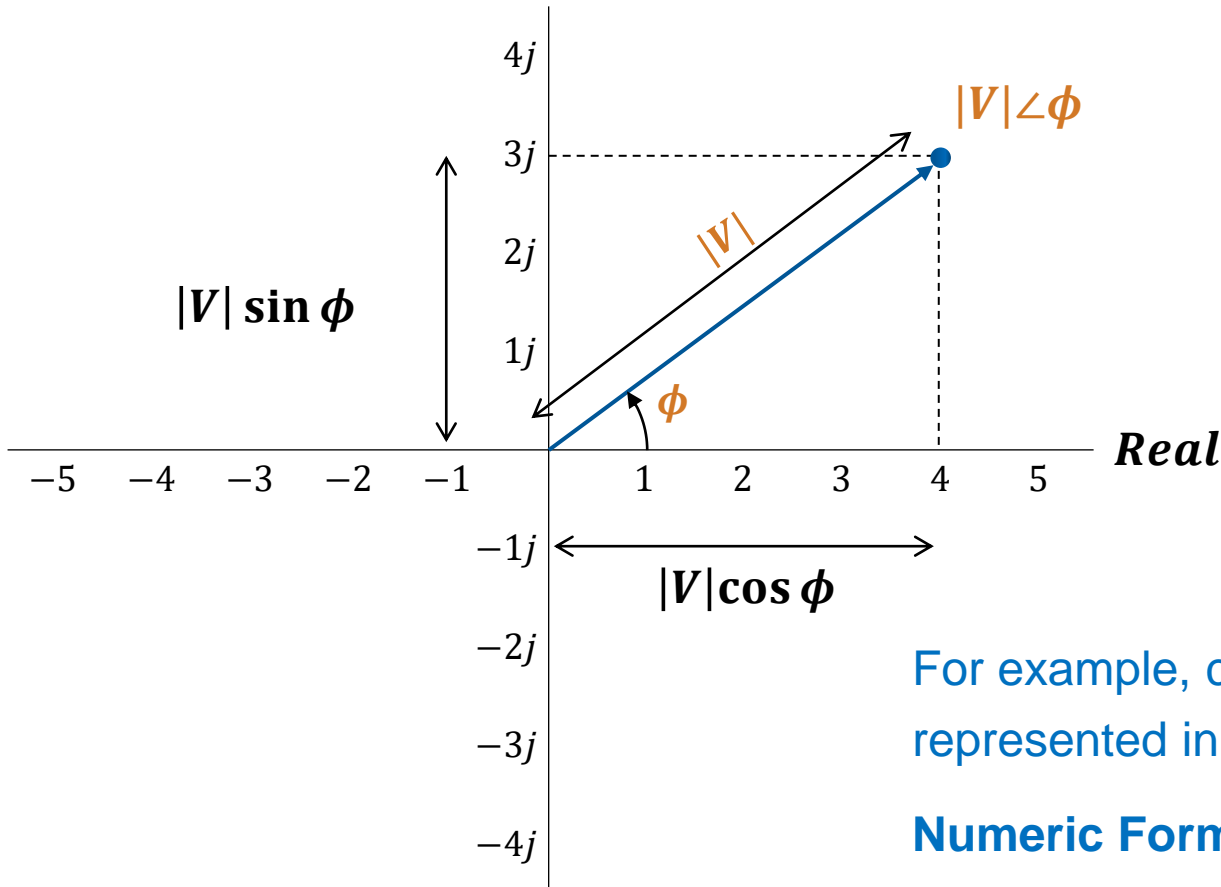
**Numeric Form –  $150\angle 25^\circ$**

**Visual Form –**



# Phasor

*Imaginary*

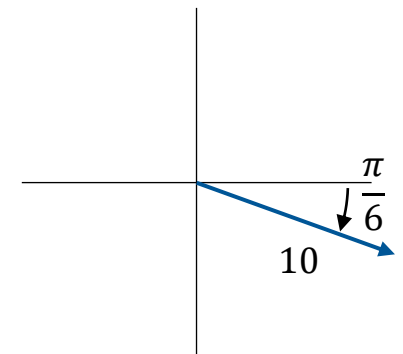


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- For all AC steady-state analysis,  $|V|$  and  $\phi$  are all we need to get meaningful results
- AC steady-state analysis – this assumes frequency  $\omega$  does not change

For example, current  $i = 10 \cos(50t - \frac{\pi}{6})$  may be represented in the phasor form as follows:

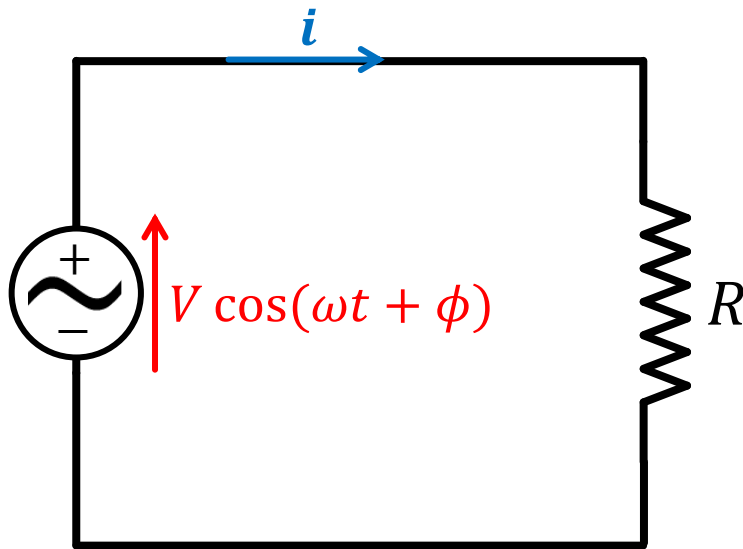
**Numeric Form –  $10\angle\frac{\pi}{6}$**

**Visual Form –**





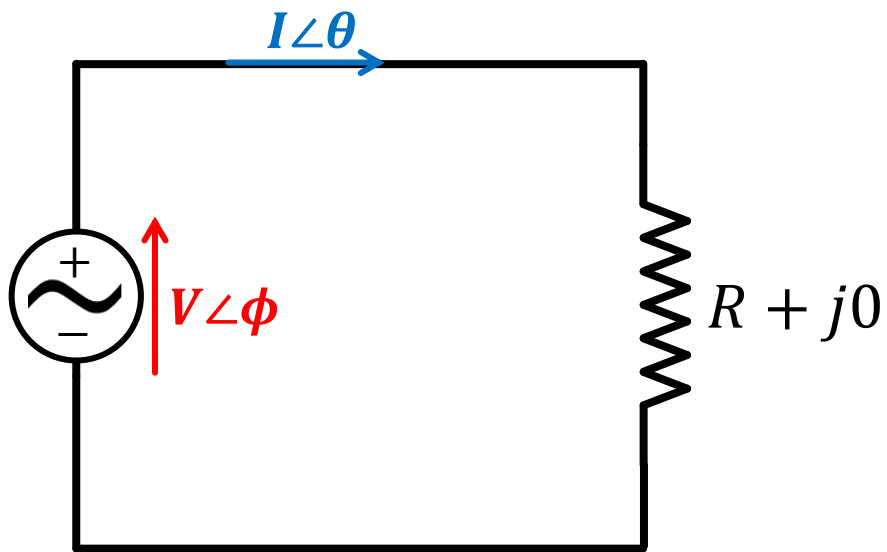
# Phasors in Resistive Circuit



- Convert all variables to **phasors** or to **complex form**
- Apply the usual – **Kirchhoff's & Ohm's** Laws
- Solve the circuit like you did earlier – only difference being you are **now using complex numbers!**



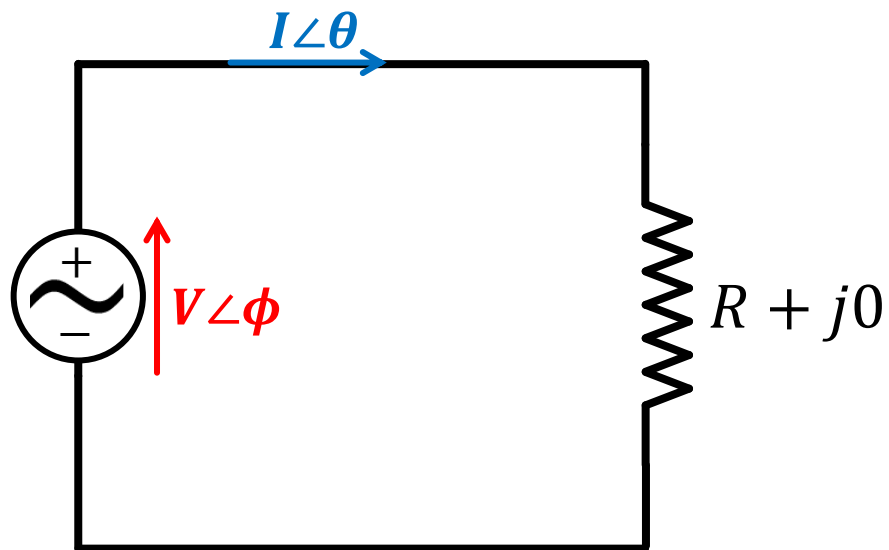
# Phasors in Resistive Circuit



- ~~Convert all variables to phasors or to complex form~~
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# Phasors in Resistive Circuit

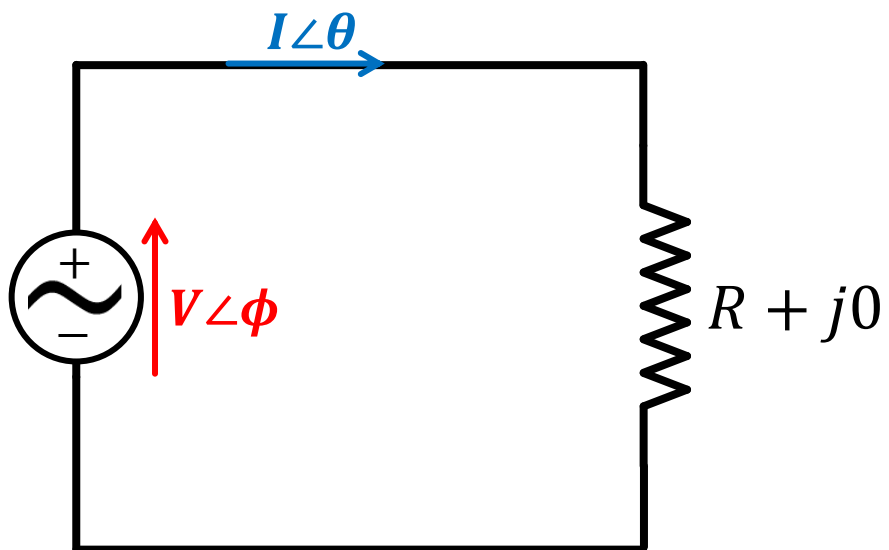


$$v = iR$$
$$V\angle\phi = IR\angle\theta$$
$$I\angle\theta = \frac{V}{R}\angle\phi$$

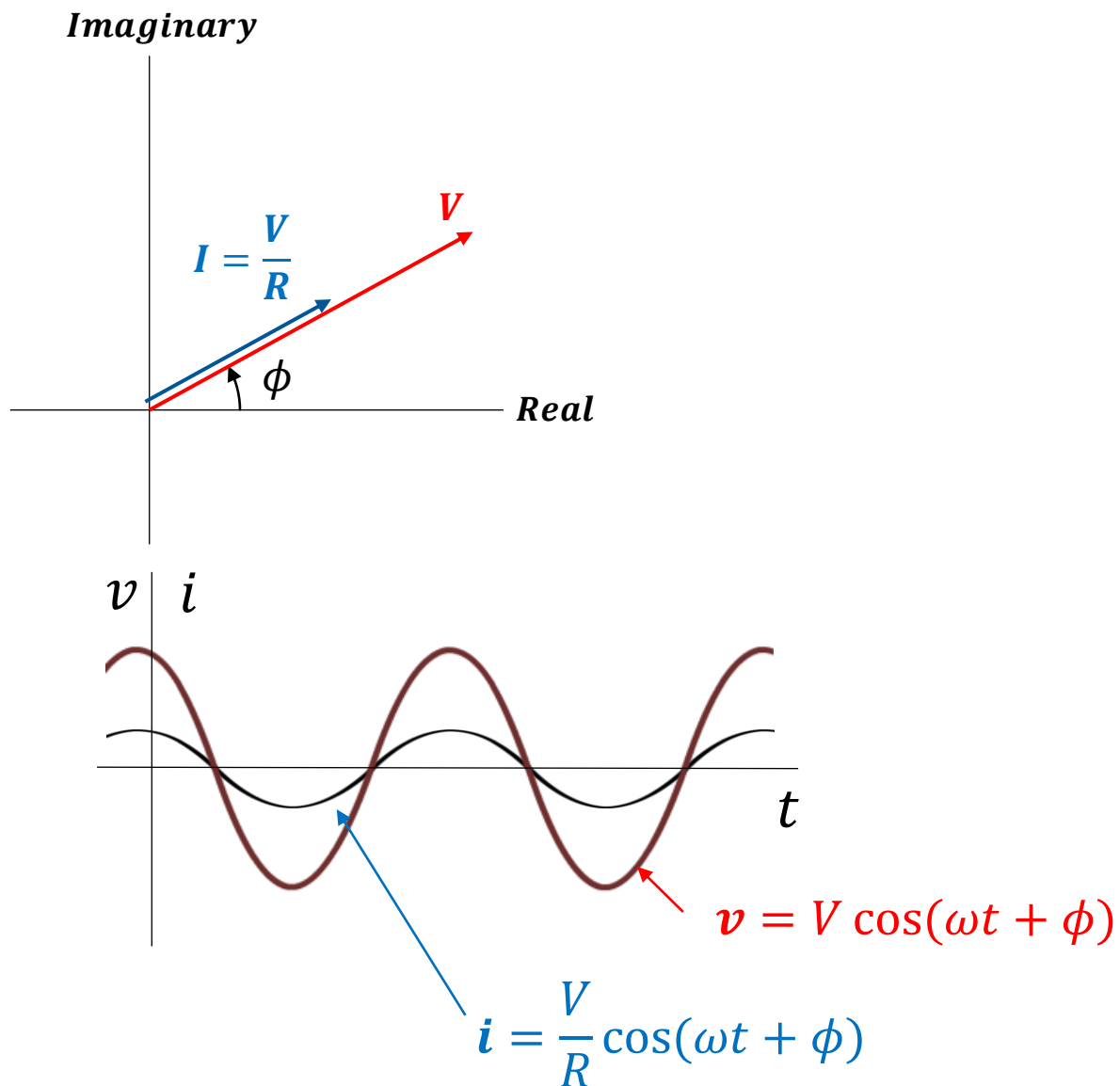
- ~~Convert all variables to phasors or to complex form~~
- ~~Apply the usual – Kirchhoff's & Ohm's Laws~~
- Solve the circuit like you did earlier – only difference being you are **now using complex numbers!**



# Phasors in Resistive Circuit



$$v = iR$$
$$V \angle \phi = IR \angle \theta$$
$$I \angle \theta = \frac{V}{R} \angle \phi$$







**Phasors are not very useful for purely resistive circuits!**

**In resistive circuits, as there is no storage of energy in the resistive element, the current is always in phase with the voltage**

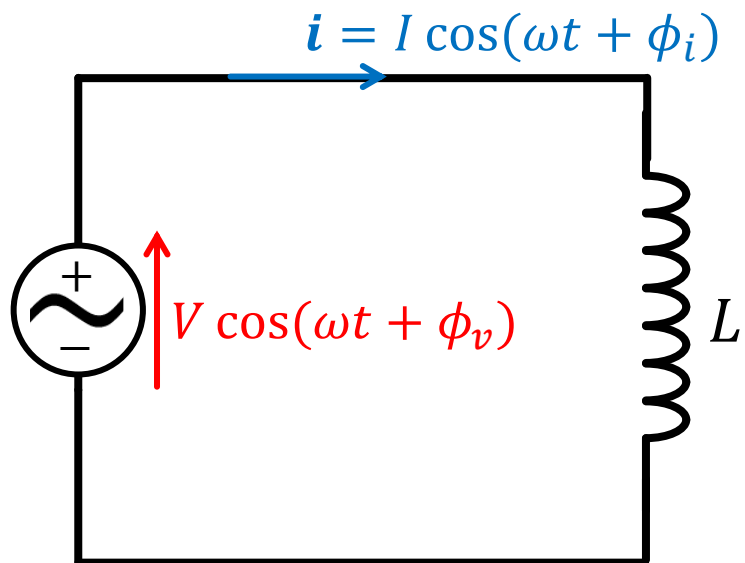
**But what about reactive elements?**

**Due to energy storage (and release) from inductors and capacitors, current is not in phase with voltage**

**This is where phasors come in handy – lets you avoid solving tedious differential equations**



# Phasors in Inductive Circuit



We know for an inductor:  $v = L \frac{di}{dt}$

$$v = V \cos(\omega t + \phi_v) = \mathbf{V}e^{j(\omega t + \phi_v)}$$

$$i = I \cos(\omega t + \phi_i) = \mathbf{I}e^{j(\omega t + \phi_i)}$$

Applying this:

$$V e^{j(\omega t + \phi_v)} = L \frac{d(I e^{j(\omega t + \phi_i)})}{dt}$$

$$V e^{j(\omega t + \phi_v)} dt = L d(I e^{j(\omega t + \phi_i)})$$

$$V \int e^{j(\omega t + \phi_v)} dt = LI \int d(e^{j(\omega t + \phi_i)})$$

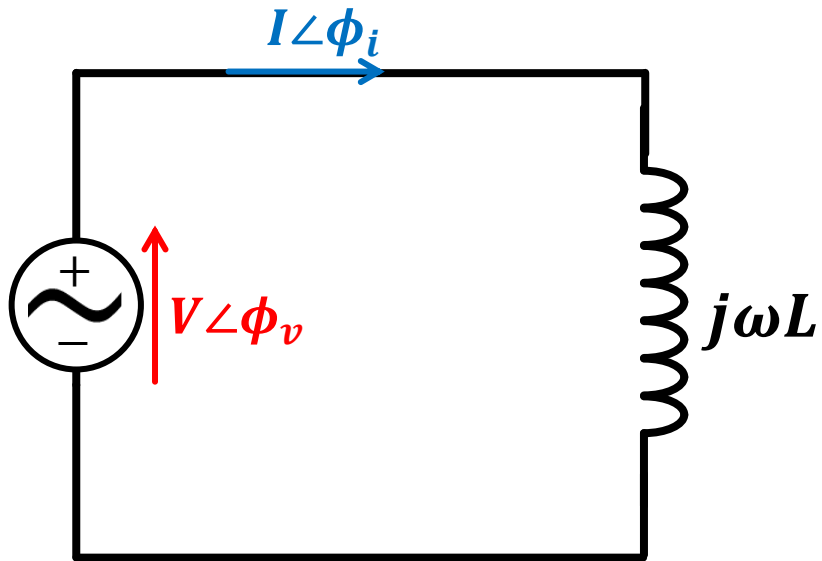
$$V \frac{e^{j(\omega t + \phi_v)}}{j\omega} = LI e^{j(\omega t + \phi_i)}$$

$$V e^{j(\omega t + \phi_v)} = j\omega LI e^{j(\omega t + \phi_i)}$$

$$\mathbf{v} = j\omega L \mathbf{i}$$

**You do not need to learn calculus here – there is an easy way!**

# Phasors in Inductive Circuit



Convert inductance to complex form

Solve using Ohm's & Kirchhoff's Laws

We know for an inductor:  $v = L \frac{di}{dt}$

$$v = V \cos(\omega t + \phi_v) = \mathbf{V}e^{j(\omega t + \phi_v)}$$

$$i = I \cos(\omega t + \phi_i) = \mathbf{I}e^{j(\omega t + \phi_i)}$$

Applying this:

$$V e^{j(\omega t + \phi_v)} = L \frac{d(I e^{j(\omega t + \phi_i)})}{dt}$$

$$V e^{j(\omega t + \phi_v)} dt = L d(I e^{j(\omega t + \phi_i)})$$

$$V \int e^{j(\omega t + \phi_v)} dt = LI \int d(e^{j(\omega t + \phi_i)})$$

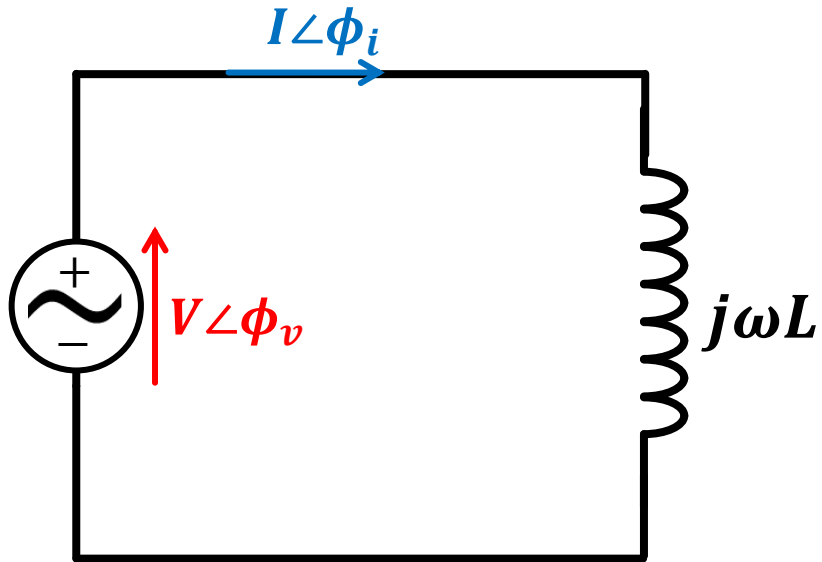
$$V \frac{e^{j(\omega t + \phi_v)}}{j\omega} = LI e^{j(\omega t + \phi_i)}$$

$$V e^{j(\omega t + \phi_v)} = j\omega LI e^{j(\omega t + \phi_i)}$$

$$\mathbf{v} = \mathbf{j\omega Li}$$

**You do not need to learn calculus here – there is an easy way!**

# Phasors in Inductive Circuit



Convert inductance to complex form

Solve using Ohm's & Kirchhoff's Laws

Ohm's Law:

$$V = IR$$

But this needs to be generalised to incorporate complex "resistance" – **reactance** – symbol  $X$

$$v = iX$$

$$V\angle\phi_v = I\angle\phi_i X$$

$$V\angle\phi_v = I\angle\phi_i j\omega L$$

$$\frac{V}{j\omega L} \angle\phi_v = I\angle\phi_i$$

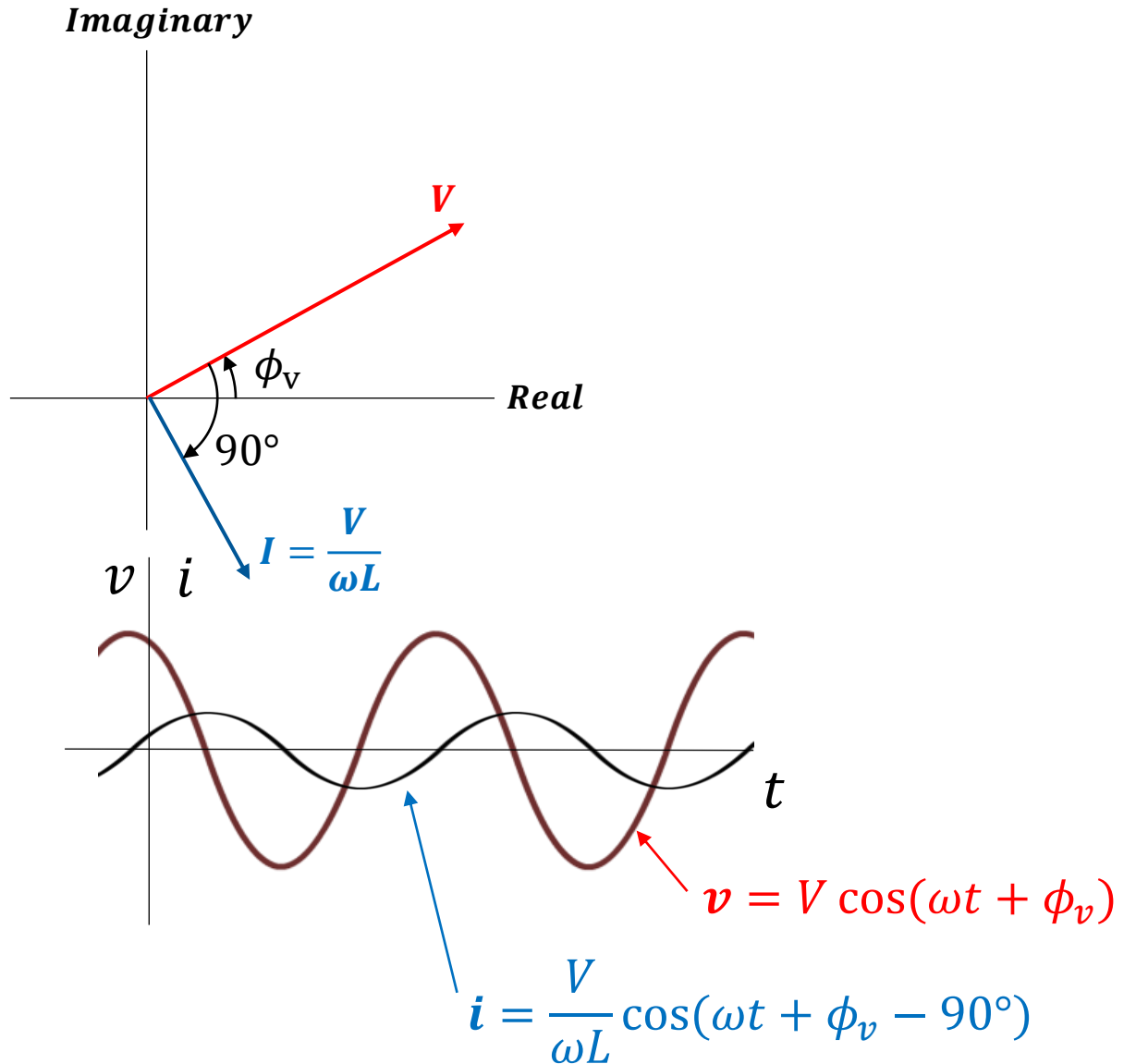
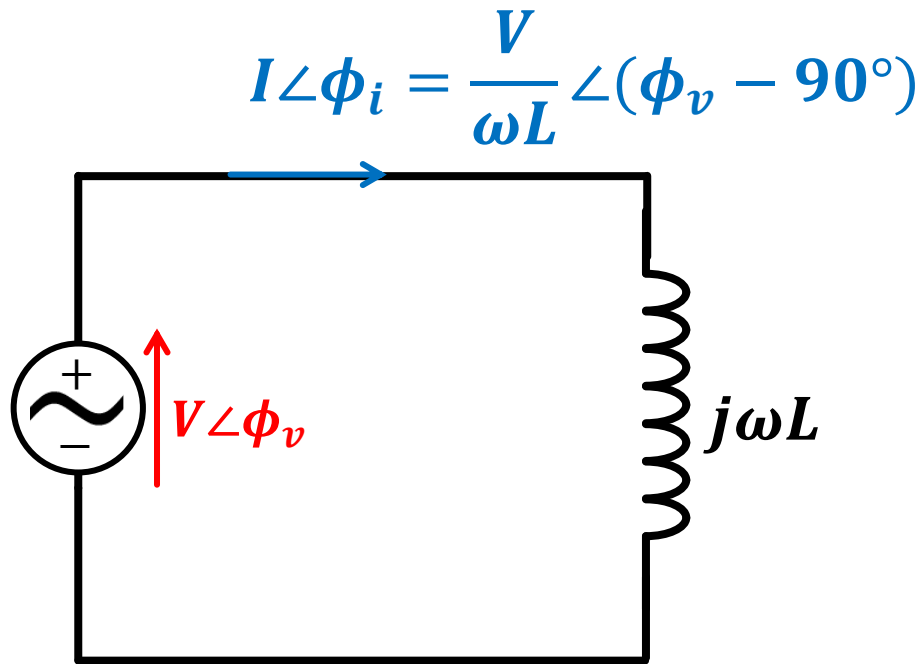
Now remember complex number division:

$$\left[ \frac{V}{\omega L} \angle\phi_v \right] \div j1 = I\angle\phi_i$$

$$\left[ \frac{V}{\omega L} \angle\phi_v \right] \div 1\angle 90^\circ = I\angle\phi_i$$

$$\frac{V}{\omega L} \angle(\phi_v - 90^\circ) = I\angle\phi_i$$

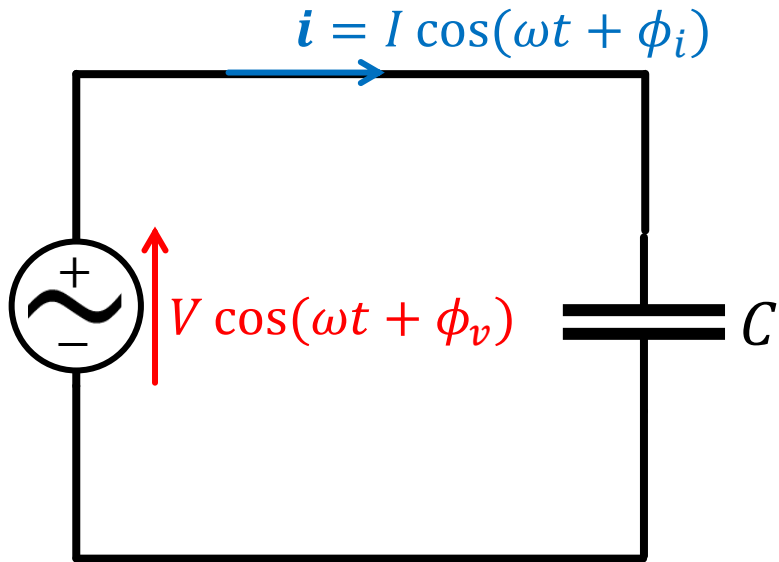
# Phasors in Inductive Circuit



In purely inductive circuit, the **current**

**LAGS voltage** by  $90^\circ$  or  $\frac{\pi}{2}$  radians

# Phasors in Capacitive Circuit



We know for a capacitor:  $i = C \frac{dv}{dt}$

$$v = V \cos(\omega t + \phi_v) = \mathbf{V}e^{j(\omega t + \phi_v)}$$

$$i = I \cos(\omega t + \phi_i) = \mathbf{I}e^{j(\omega t + \phi_i)}$$

Applying this:

$$i = C \frac{d(Ve^{j(\omega t + \phi_v)})}{dt}$$

$$i = CV \frac{d(e^{j(\omega t + \phi_v)})}{dt}$$

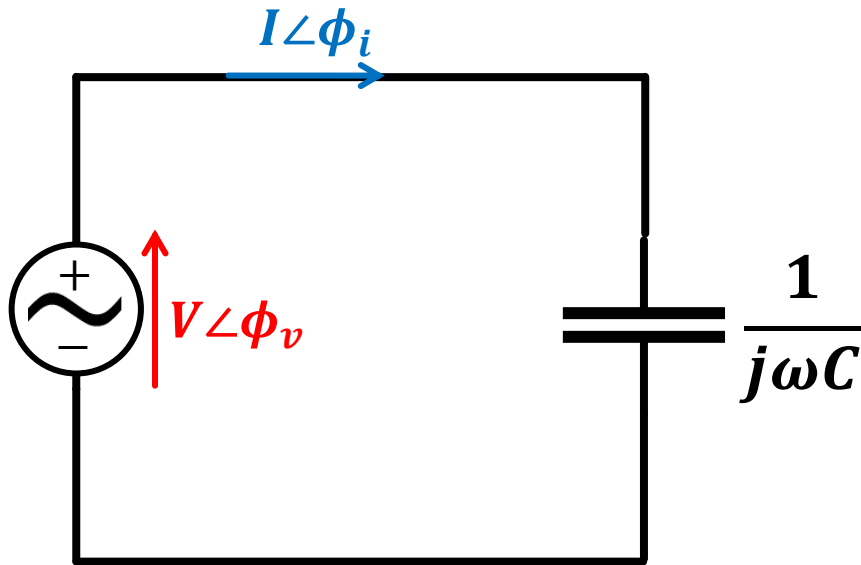
$$i = j\omega CV e^{j(\omega t + \phi_v)}$$

$$\frac{1}{j\omega C} i = V e^{j(\omega t + \phi_v)}$$

$$\mathbf{v} = \frac{\mathbf{1}}{j\omega C} \mathbf{i}$$

**You do not need to learn calculus here – there is an easy way!**

# Phasors in Capacitive Circuit



Convert capacitance to reactance

Solve using Ohm's & Kirchhoff's Laws

We know for a capacitor:  $i = C \frac{dv}{dt}$

$$v = V \cos(\omega t + \phi_v) = V e^{j(\omega t + \phi_v)}$$

$$i = I \cos(\omega t + \phi_i) = I e^{j(\omega t + \phi_i)}$$

Applying this:

$$i = C \frac{d(V e^{j(\omega t + \phi_v)})}{dt}$$

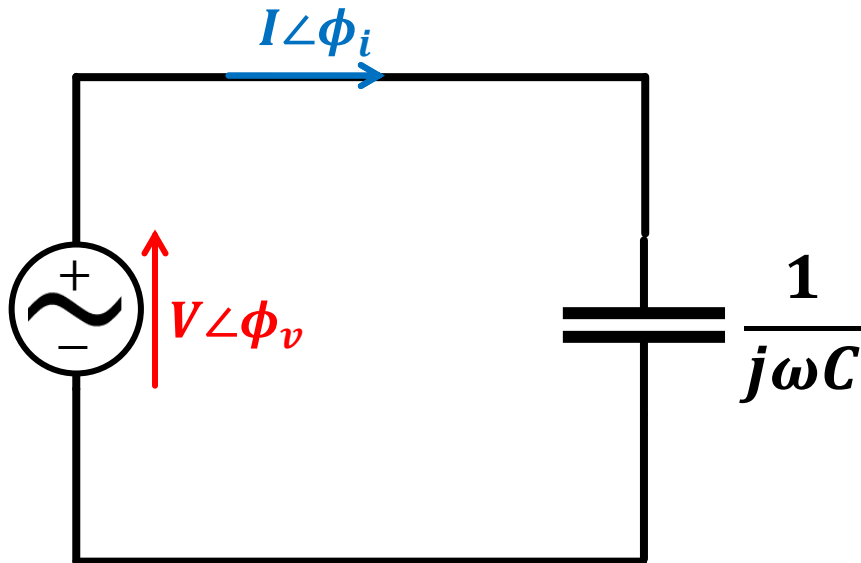
$$i = CV \frac{d(e^{j(\omega t + \phi_v)})}{dt}$$

$$i = j\omega CV e^{j(\omega t + \phi_v)}$$

$$\frac{1}{j\omega C} i = V e^{j(\omega t + \phi_v)}$$

$$v = \frac{1}{j\omega C} i$$

**You do not need to learn calculus here – there is an easy way!**



**Convert capacitance to reactance**

**Solve using Ohm's & Kirchhoff's Laws**

Ohm's Law:

$$V = IR$$

But this needs to be generalised to incorporate complex "resistance" – **reactance** – symbol  $X$

$$v = iX$$

$$V\angle\phi_v = I\angle\phi_i X$$

$$V\angle\phi_v = I\angle\phi_i \frac{1}{j\omega C}$$

$$Vj\omega C\angle\phi_v = I\angle\phi_i$$

Now remember complex number multiplication:

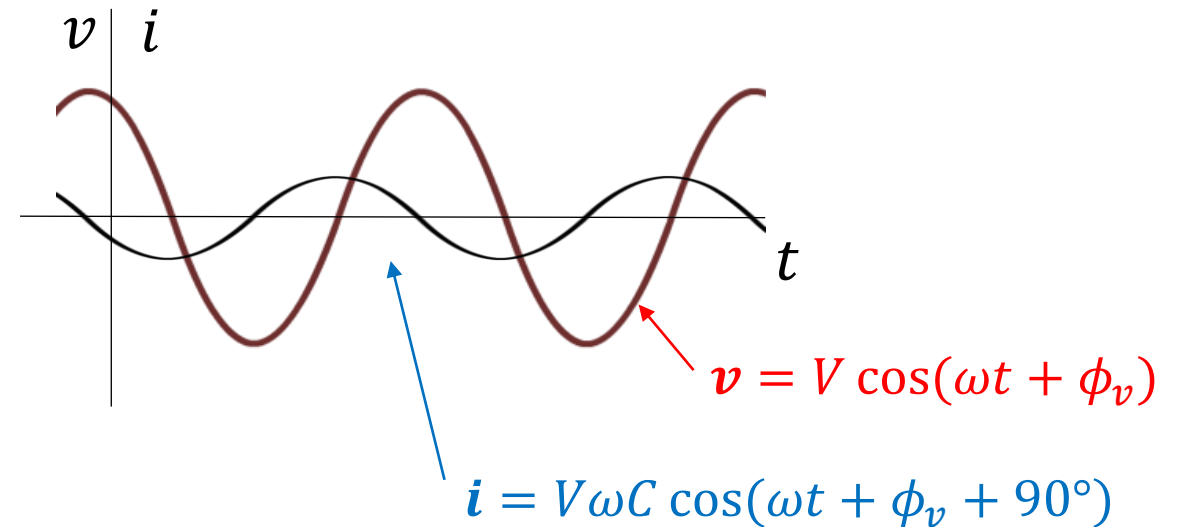
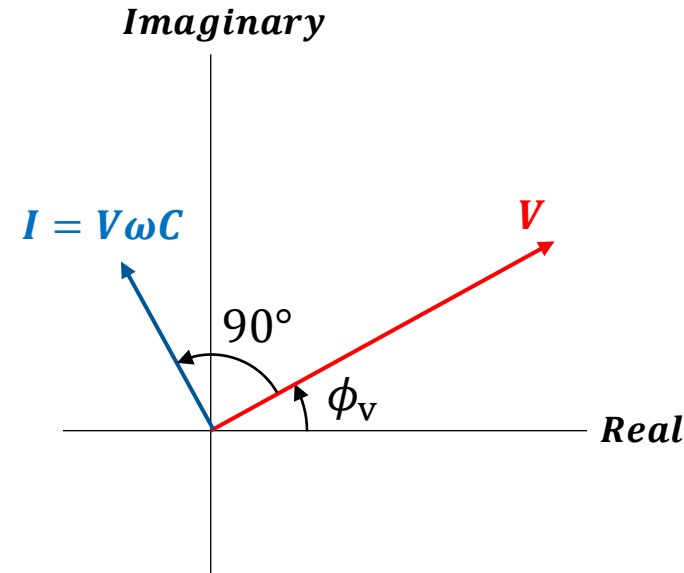
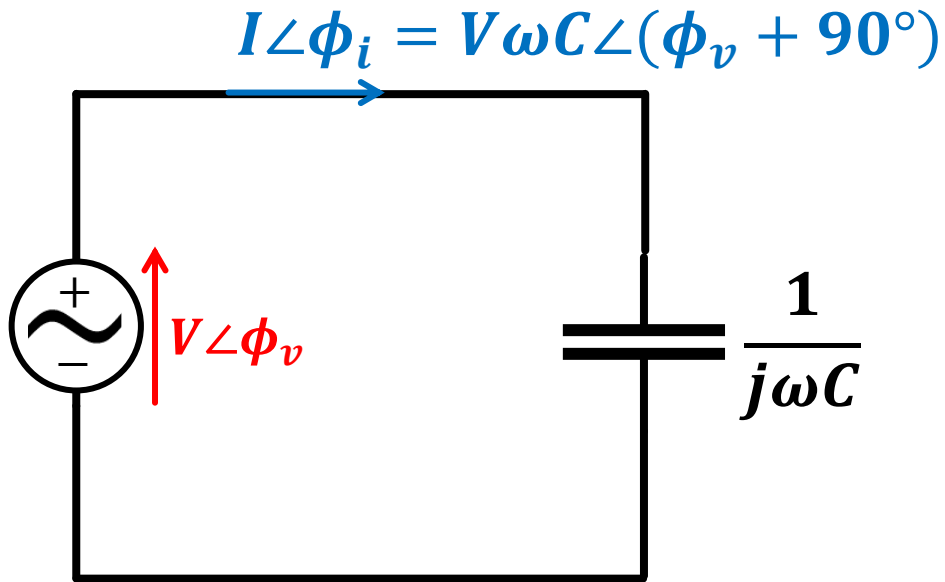
$$[V\omega C\angle\phi_v] \times j1 = I\angle\phi_i$$

$$[V\omega C\angle\phi_v] \times 1\angle 90^\circ = I\angle\phi_i$$

$$V\omega C\angle(\phi_v + 90^\circ) = I\angle\phi_i$$



# Phasors in Capacitive Circuit

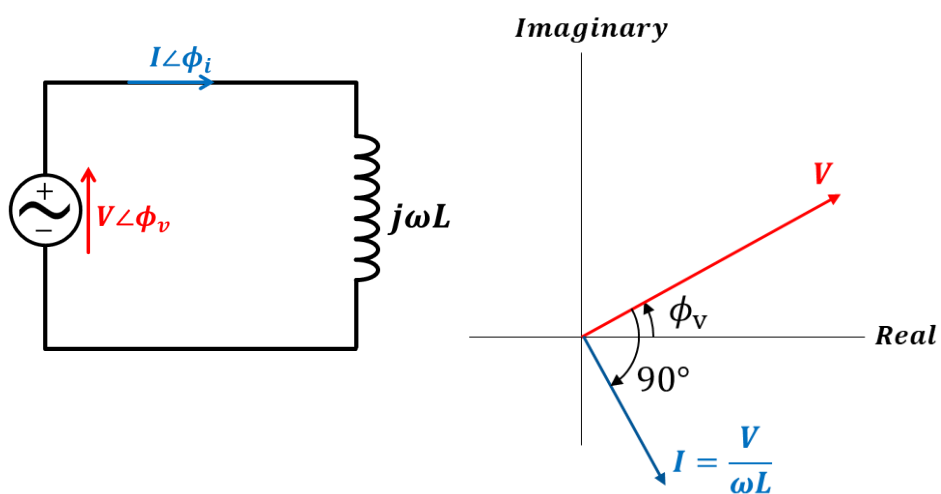


In **purely capacitive** circuit, the **current**

**LEADS voltage** by  $90^\circ$  or  $\frac{\pi}{2}$  radians

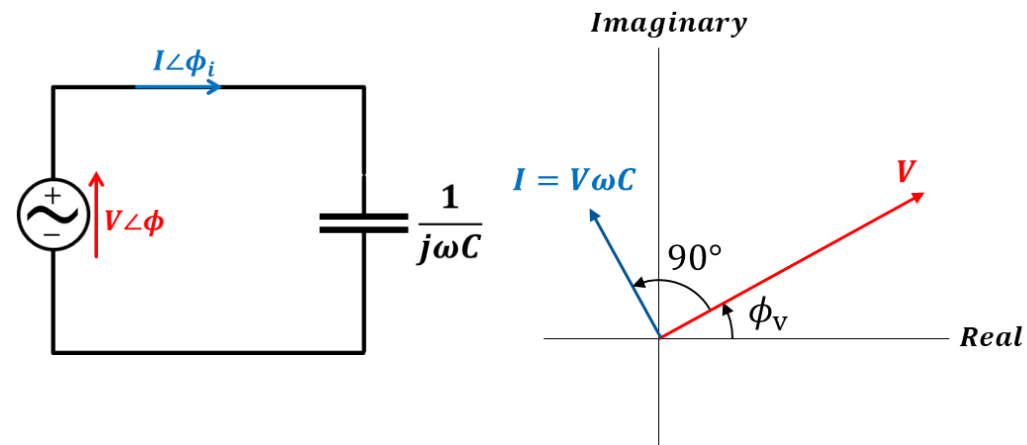


# Reactive Circuits – Summary



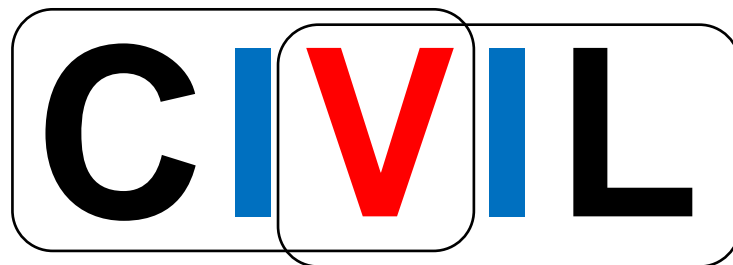
$$X_L = j\omega L$$

**current LAGS voltage** by  $90^\circ$  or  $\frac{\pi}{2}$  radians

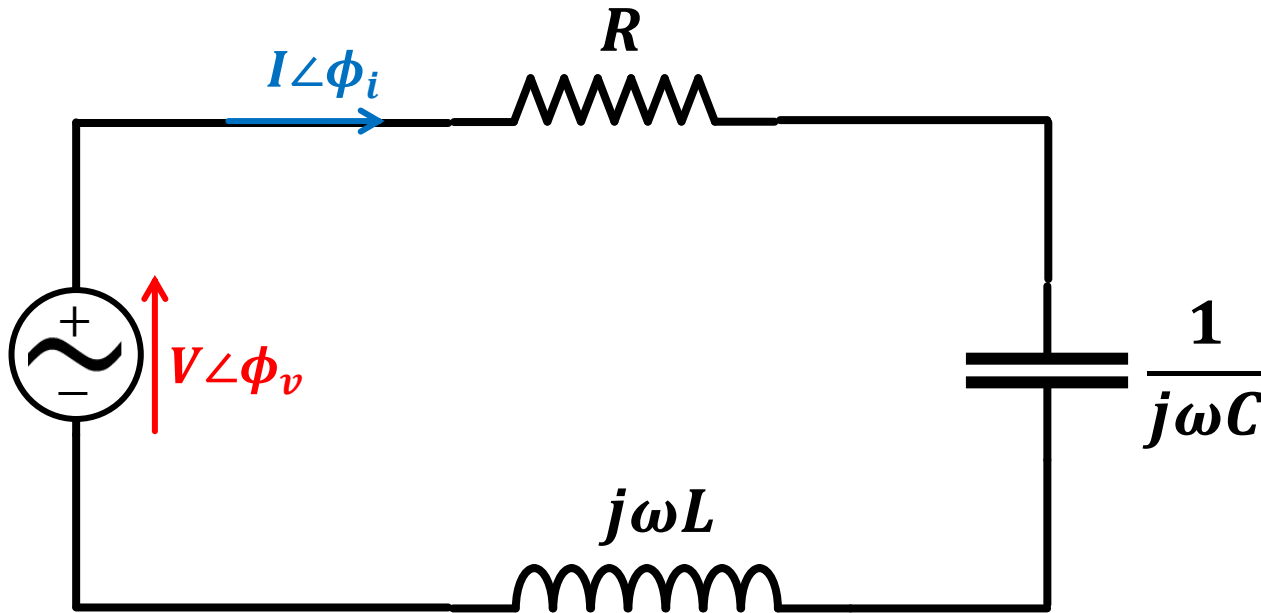


$$X_C = \frac{1}{j\omega C}$$

**current LEADS voltage** by  $90^\circ$  or  $\frac{\pi}{2}$  radians



# The Real Circuit (Resistive + Reactive)



$$\text{Impedance} = Z = R + j\omega L + \frac{1}{j\omega C}$$

It is practically impossible to have a purely reactive circuit – any inductor or capacitor would have some **parasitic resistance** values

Remember we discussed Impedance in the previous lecture!

**Impedance** indicates how much a load “impedes” or **hinders** the **flow of current** through itself on application of a **set amount of voltage** across it

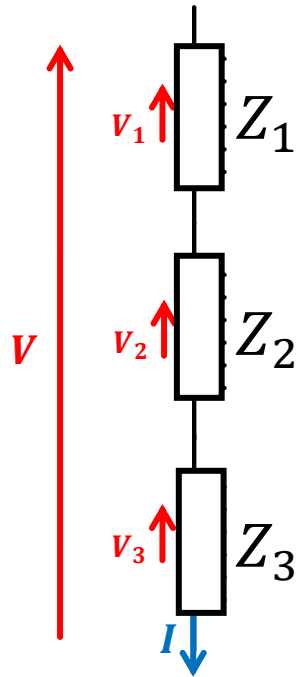
**Generalisation of Resistance** – now incorporates AC circuits as well

**Ohm’s Law still applies!**

# The Real Circuit (Resistive + Reactive)

## Series

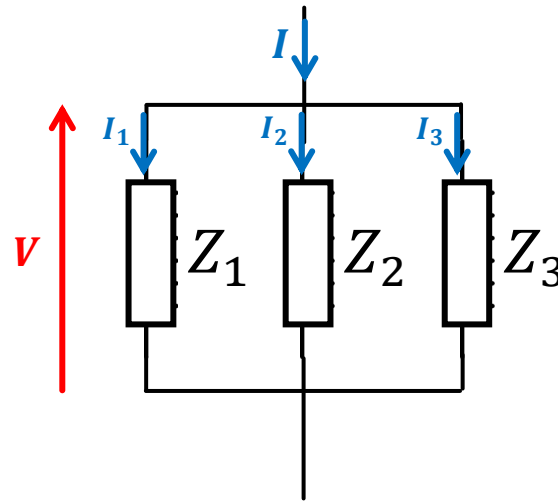
When two (or more) elements are connected together head-to-toe



$$Z = \sum Z_i$$

## Parallel

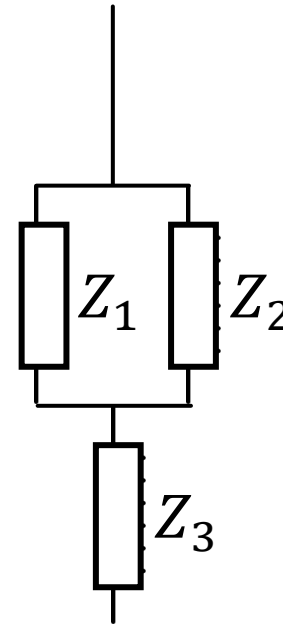
When two (or more) elements are connected head-to-head and toe-to-toe



$$\frac{1}{Z} = \sum \frac{1}{Z_i}$$

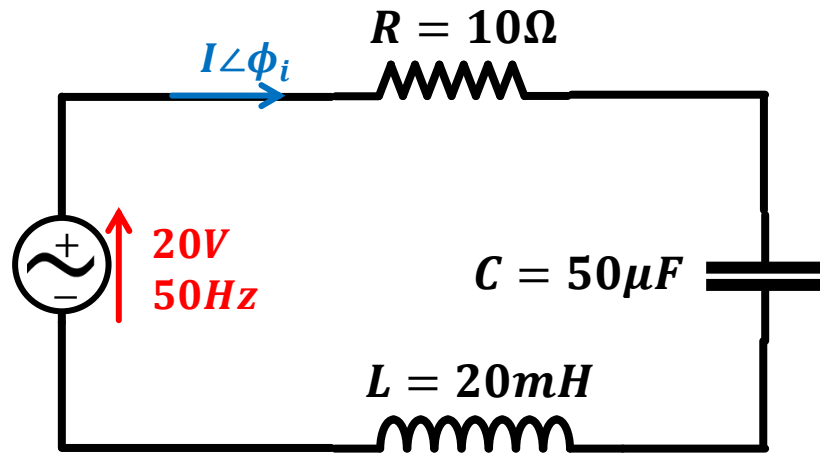
## Series-Parallel

Combination of the both

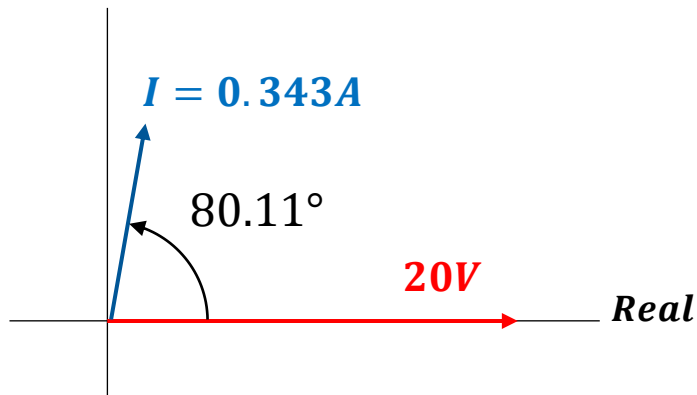


Break the circuit up into series and parallel and solve individually

# Example of Real Circuit



Imaginary



$$Z_R = 10\Omega$$

$$Z_L = j\omega L = j2\pi fL = j2 \times 3.14 \times 50 \times 20 \times 10^{-3} = j6.28\Omega$$

$$Z_C = \frac{1}{j\omega C} = \frac{1}{j2\pi fC} = \frac{-j}{2 \times 3.14 \times 50 \times 50 \times 10^{-6}} = -j63.66\Omega$$

The **three elements** are clearly in **series**

$$Z = Z_R + Z_L + Z_C = 10 + j(6.28 - 63.69) = 10 - j57.38$$

Applying **Ohm's Law**, we need to divide V by Z, remember, for division, we need complex numbers in **polar form**

$$|Z| = \sqrt{10^2 + 57.41^2} = \sqrt{3395.91} = 58.24$$

$$\angle Z = \tan^{-1} \frac{-57.41}{10} = -80.11^\circ$$

Applying **Ohm's Law**

$$I = \frac{V}{Z} = \frac{20\angle 0^\circ}{58.24\angle -80.11^\circ} = 0.343\angle 80.11^\circ$$

When no info on phase offset for voltage provided, no harm in setting it to 0°, makes calculations easier!



- Fundamentals of **Alternating Current – or AC**
  - DC v AC circuit study – waveforms a **function of time!**
  - **Sinusoidal** waveform – voltage & current
  - **Complex Numbers**
- AC circuits
  - **Phasor** study – simple way to solve time-varying circuits
  - Resistor, Inductor, Capacitor in phasor form - **CIVIL**
  - **Reactance** – Purely reactive circuits (just inductor/capacitor)
  - **Impedance** – Resistance & Reactance
- Power in AC circuits
  - **Active v Reactive v Apparent Power**
  - **Power Factor**
  - **Resonance**



# Root Mean Square (RMS)

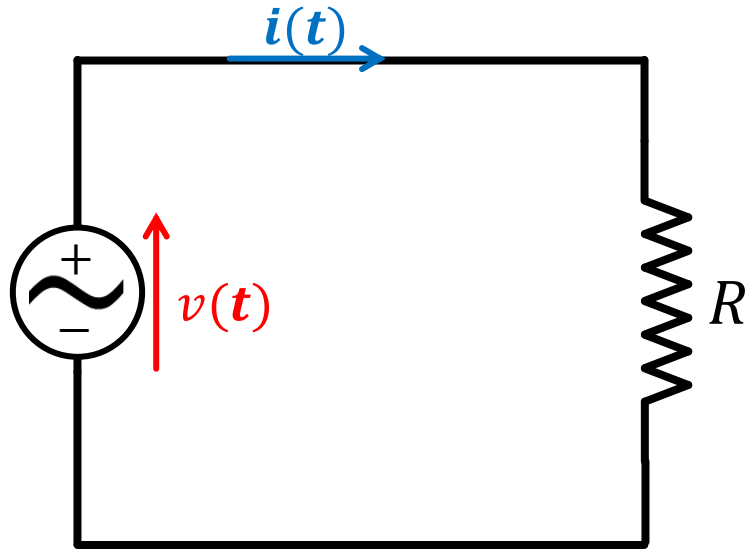
- In mathematics, the **root-mean-square** (or **RMS**) of a set of numbers  $x_i$  is defined as the square root of the arithmetic mean of the squares of the set

$$\underline{x} = \sqrt{\frac{x_1^2 + x_2^2 + x_3^2 + \dots + x_n^2}{n}} = \sqrt{\frac{\sum x_i^2}{n}}$$

- When dealing with AC applications, the amplitude of voltage or current is seldom used (we will see shortly why – power)
- Hence, AC ammeters/voltmeters are invariably calibrated for RMS value – not peak/amplitude
- For all **sinusoidal waves**, the RMS value is  $\frac{1}{\sqrt{2}} = 0.707$  times the amplitude
- It is much more convenient to make the **length of phasors** represent **RMS** instead of amplitude
- Going forward, we will deal with **only RMS values** when studying AC

$$\text{RMS value of } V = V_{rms} = \frac{|V|}{\sqrt{2}} = 0.707V$$

# Power in Resistive Circuit



$$v(t) = V \cos \omega t$$

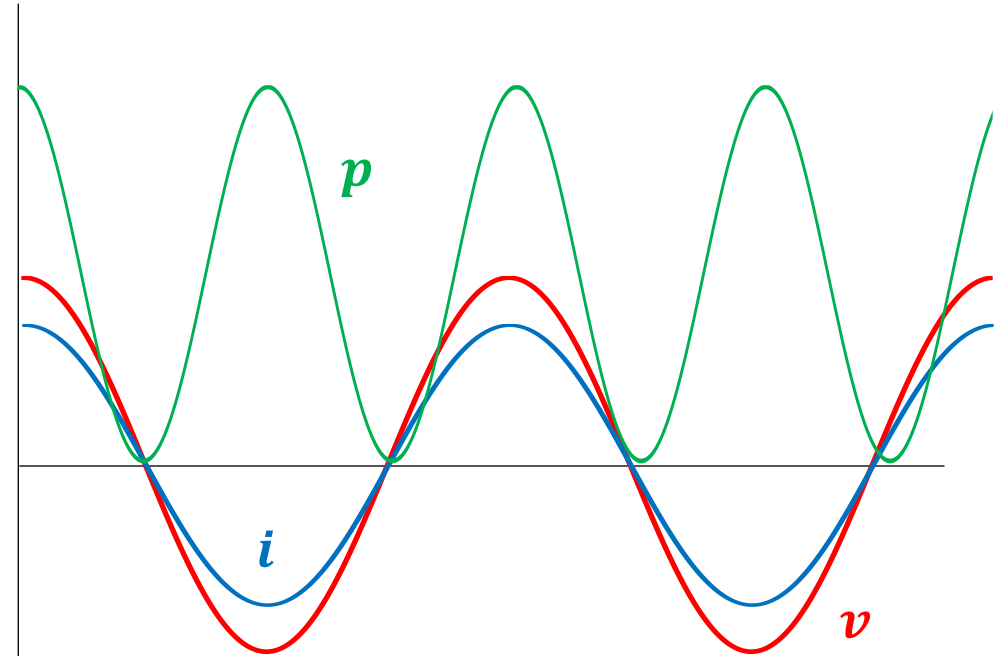
$$i(t) = I \cos \omega t$$

Instantaneous power

$$p(t) = v(t) \times i(t)$$

$$p(t) = V \cos \omega t \times I \cos \omega t$$

$$p(t) = \frac{VI}{2} (1 + \cos 2\omega t) = \frac{I^2 R}{2} (1 + \cos 2\omega t) = \frac{V^2}{2R} (1 + \cos 2\omega t)$$



Average power – integrate over full cycle

$$P_{avg} = \int \frac{VI}{2} (1 + \cos 2\omega t)$$

$$P_{avg} = \frac{VI}{2} + 0$$

$$P_{avg} = \frac{V_m I_m}{\sqrt{2} \sqrt{2}} = V_{rms} I_{rms}$$





## Proof (don't learn)

$$\begin{aligned} P_{avg} &= \frac{1}{T} \int_0^T p(t) dt \\ &= \frac{1}{T} \int_0^T v(t)i(t) dt \\ &= \frac{1}{T} \int_0^T V \cos(\omega t)I \cos(\omega t) dt \\ &= \frac{1}{T} \int_0^T \frac{VI}{2} \{1 + \cos(2\omega t)\} dt \\ &= \frac{1}{T} \int_0^T \frac{VI}{2} dt + \frac{1}{T} \int_0^T \frac{V_m I_m}{2} \{\cos(2\omega t)\} dt \\ &= \frac{VI}{2} - \frac{1}{\omega T} \int_0^{2\pi} \frac{V_m I_m}{2} \{\cos(2\omega t)\} d\omega t \\ &= \frac{VI}{2} = V_{rms} I_{rms} \end{aligned}$$

$$P_{avg} = \frac{V_m}{\sqrt{2}} \frac{I_m}{\sqrt{2}} = V_{rms} I_{rms}$$

**Remember that power in DC circuits**

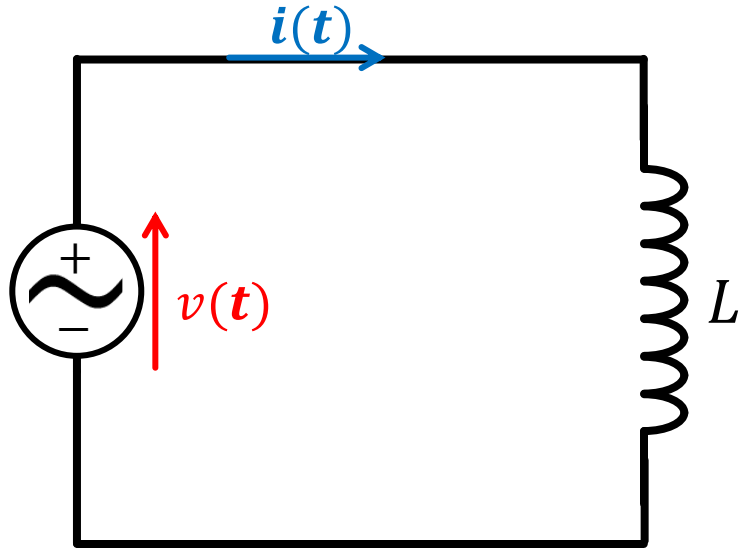
$$P = V_{dc} \times I_{dc}$$

**Equivalently, the AC counterparts for**

**$V_{dc}$  is  $V_{rms}$  and  $I_{dc}$  is  $I_{rms}$**

**That is why we always use the RMS  
value of voltage and current**

# Power in Inductive Circuit



$$v(t) = V \cos \omega t$$

$$i(t) = I \sin \omega t$$

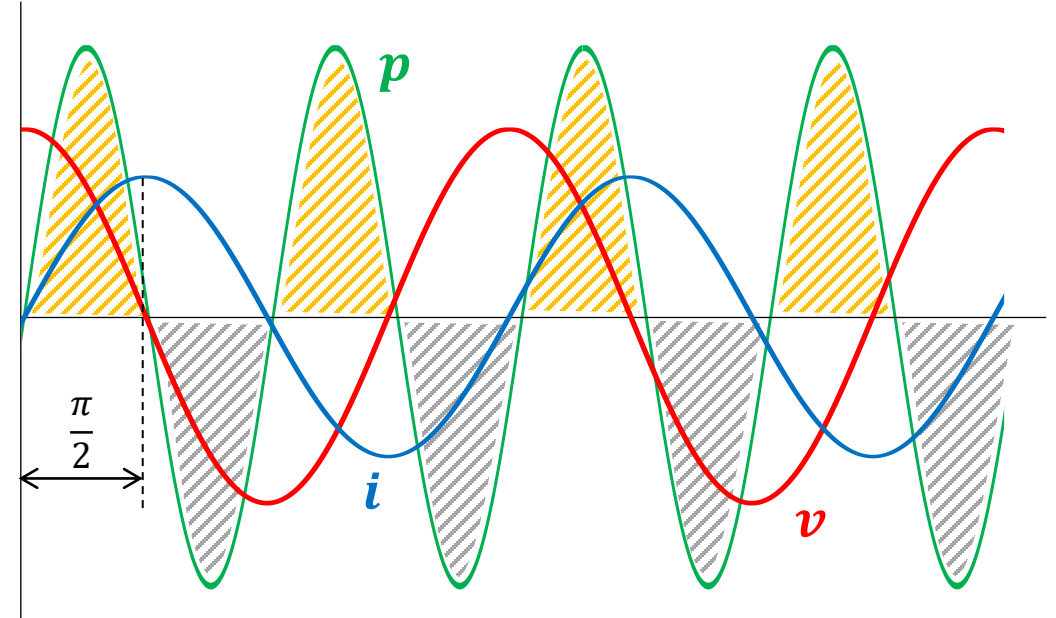
Do you know why?

Instantaneous power

$$p(t) = v(t) \times i(t)$$

$$p(t) = V \cos \omega t \times I \sin \omega t$$

$$p(t) = \frac{VI}{2} \sin 2\omega t = \frac{\omega LI^2}{2} \sin 2\omega t = \frac{V^2}{2\omega L} \sin 2\omega t$$



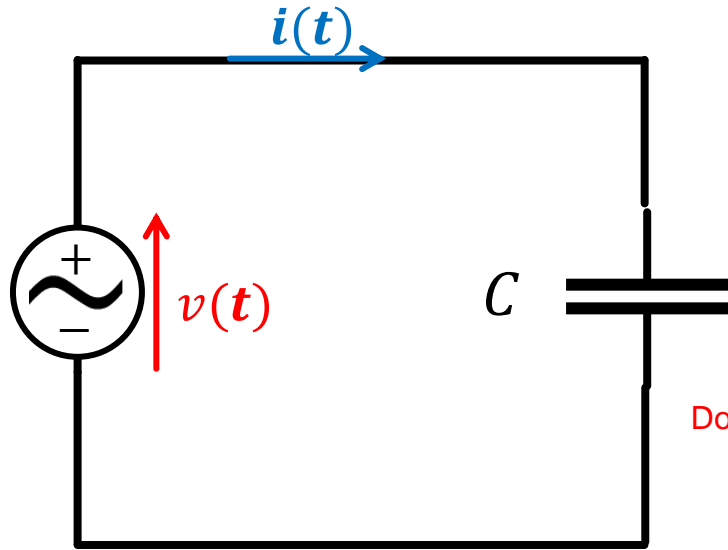
Energy absorbed from the source



Energy released to the source

**Average power is ZERO!**

# Power in Capacitive Circuit



$$v(t) = V \cos \omega t$$

$$i(t) = -I \sin \omega t$$

Do you know why?

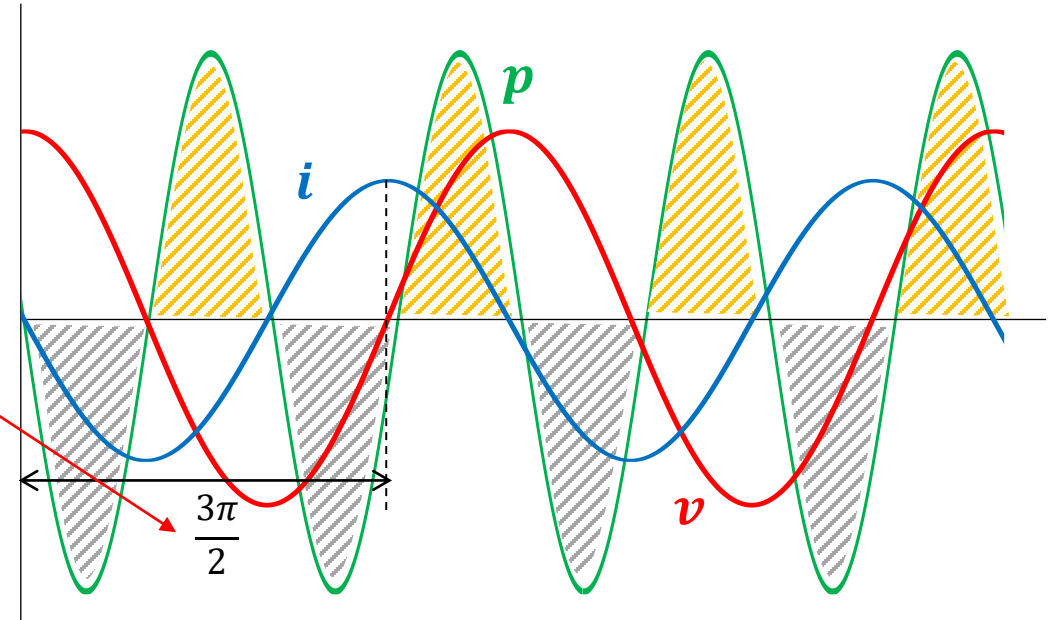
Do you know why?

Instantaneous power

$$p(t) = v(t) \times i(t)$$

$$p(t) = -V \cos \omega t \times I \sin \omega t$$

$$p(t) = \frac{-VI}{2} \sin 2\omega t = \frac{I^2}{2\omega C} \sin 2\omega t = \frac{\omega CV^2}{2} \sin 2\omega t$$



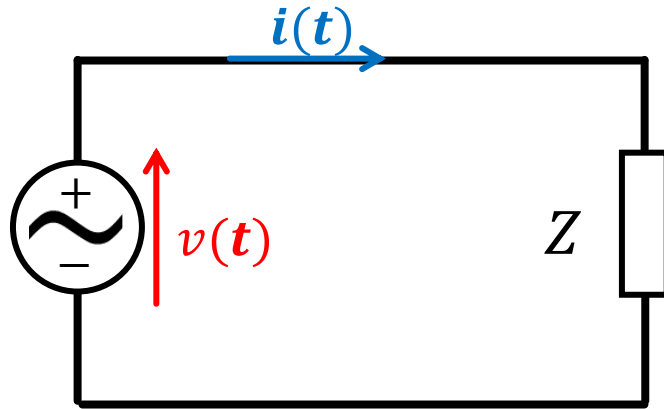
Energy absorbed from the source



Energy released to the source

**Average power is ZERO!**

# Power in Real Circuit (Resistive + Reactive)



$$v(t) = V \cos \omega t$$

$$i(t) = I \cos(\omega t + \gamma)$$

Instantaneous power

$$p(t) = v(t) \times i(t)$$

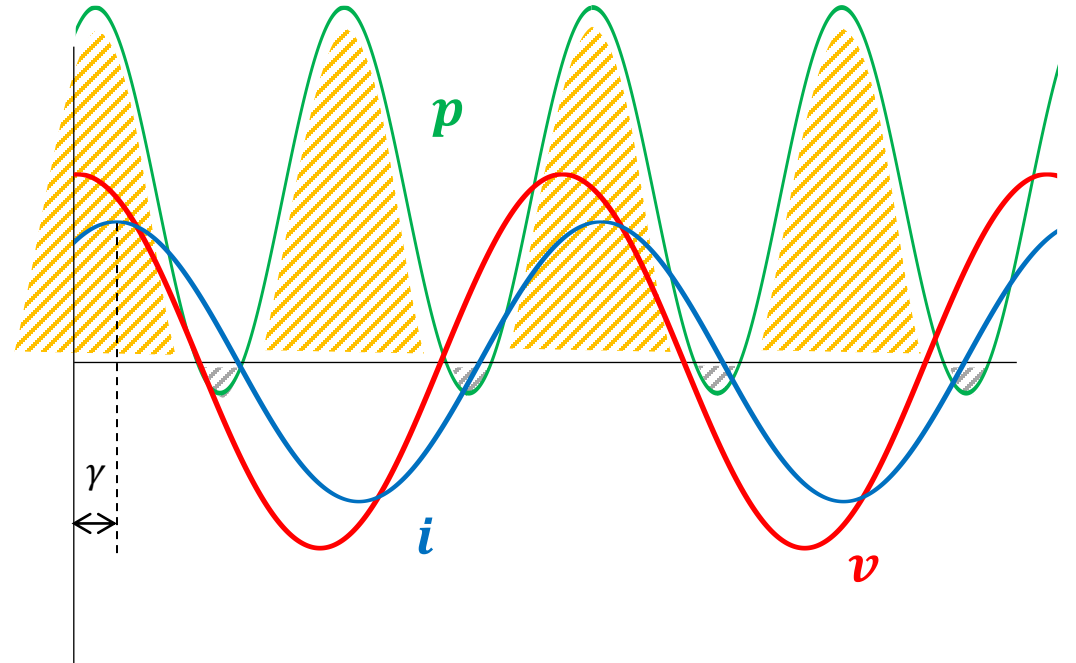
$$p(t) = V \cos \omega t \times I \cos(\omega t + \gamma)$$

$$p(t) = \frac{VI}{2} \{ \cos(\omega t - \omega t - \gamma) + \cos(\omega t + \omega t + \gamma) \}$$

$$p(t) = V_{rms} I_{rms} \cos \gamma + V_{rms} I_{rms} \cos(2\omega t + \gamma)$$

Average Power

This term averages to zero over a cycle



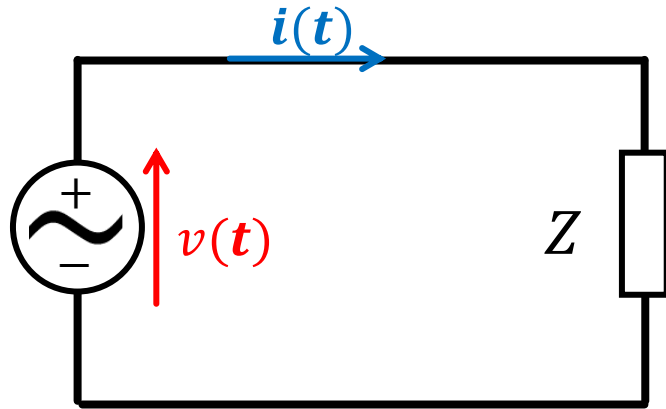
Energy absorbed from the source



Energy released to the source

Average power is  $V_{rms} I_{rms} \cos \gamma$  **Power Factor**

# Power Factor



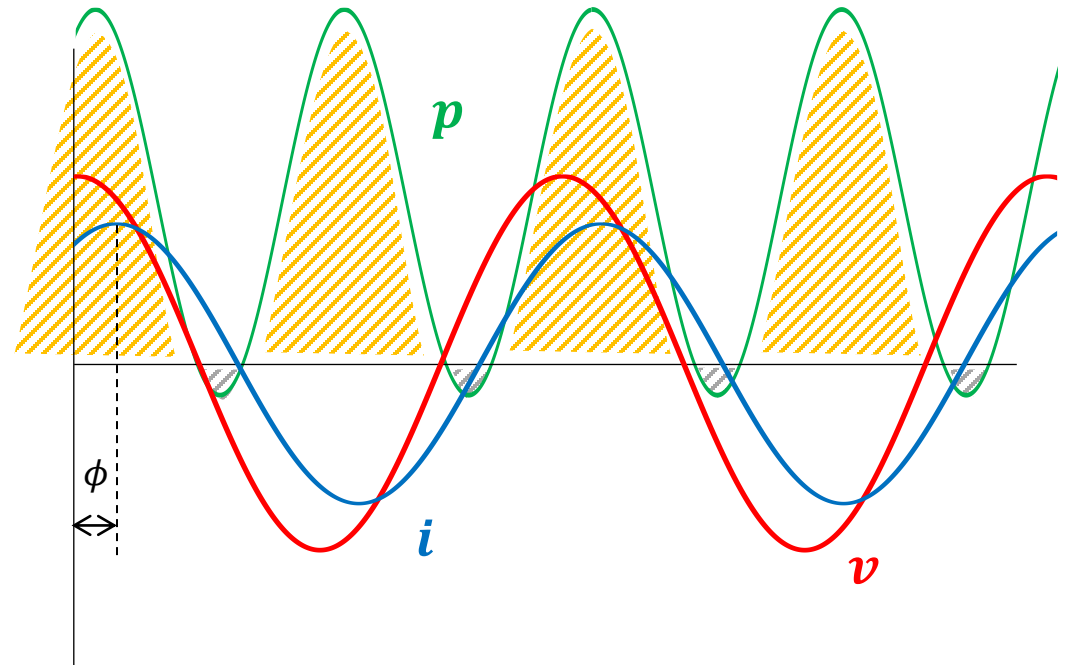
$$P_{avg} = V_{rms} I_{rms} \cos \gamma$$

$$\cos \gamma = \text{Power Factor} = PF$$

$\gamma$  is the **phase deviation** between voltage & current

**PF** tells us **what fraction of the current does useful work**

Is it phase **advance/delay**? *Does it matter?*



Energy absorbed from the source



Energy released to the source



# Power Factor

Purely Resistive Load $R$	$\gamma = 0^\circ$ $\cos \gamma = 1$	All power consumed
Purely Reactive Load $L$ or $C$	$\gamma = \pm 90^\circ$ $\cos \gamma = 0$	No <b>real power</b> consumed
Real Inductive Load $RL$ or $RLC$	$-90^\circ < \gamma < 0^\circ$ $0 < \cos \gamma < 1$	Part of <b>apparent power</b> consumed
Real Capacitive Load $RC$ or $RLC$	$0^\circ < \gamma < 90^\circ$ $0 < \cos \gamma < 1$	

## Apparent Power (symbol **S** unit **VA**)

$$S = V_{rms}I_{rms}$$

- As the name suggests, this is the amount of power that appears to be flowing from source to load
- This is not the case as over a cycle, some (or all) of this power gets returned back to source
- As the power still flows (even if it is simply thrown back-forth between source and load), losses still occur
- A good circuit should have PF very close to unity
- However, AC equipment are rated for Apparent Power as it handles both used and unused power

## Active Power (symbol **P** unit **W**)

$$P = V_{rms}I_{rms} \cos \gamma = V_{rms}I_{rms}PF = S \times PF$$

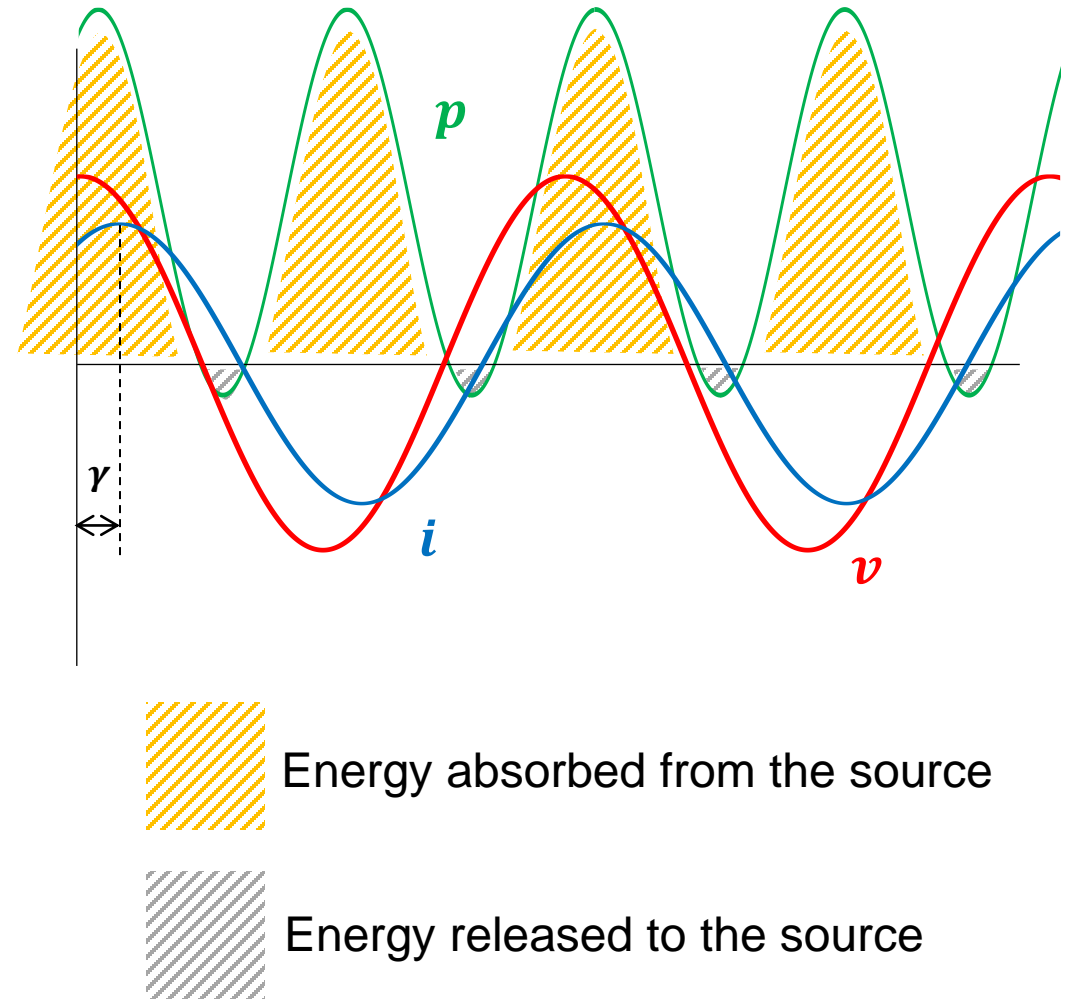
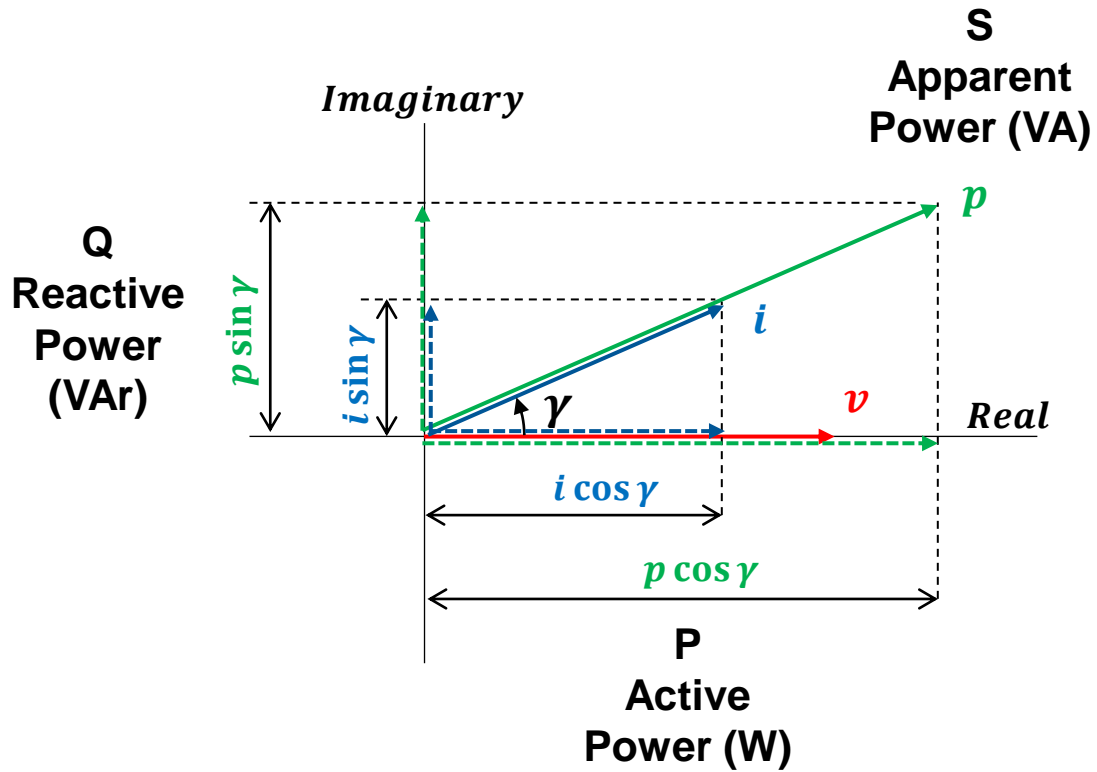
- This is the real power transferred to the load

## Reactive Power (symbol **Q** unit **VAR**)

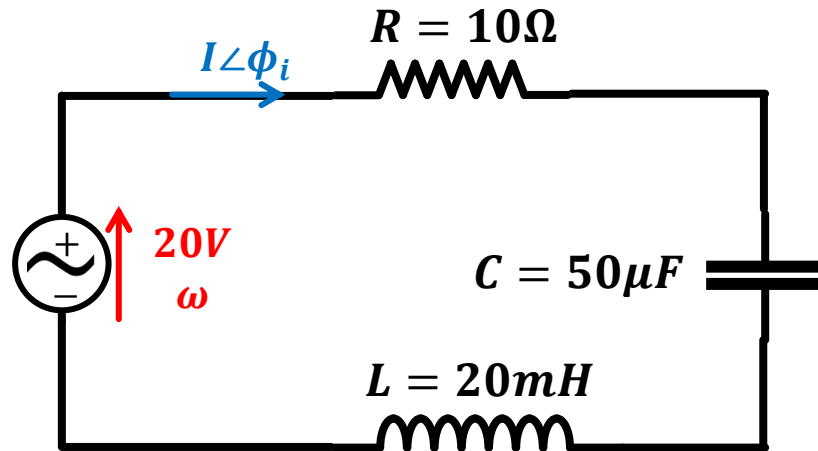
$$P = V_{rms}I_{rms} \sin \gamma = V_{rms}I_{rms} \sin \gamma = S \sin \gamma$$

- This is the purely unused power exchanged between the source and load

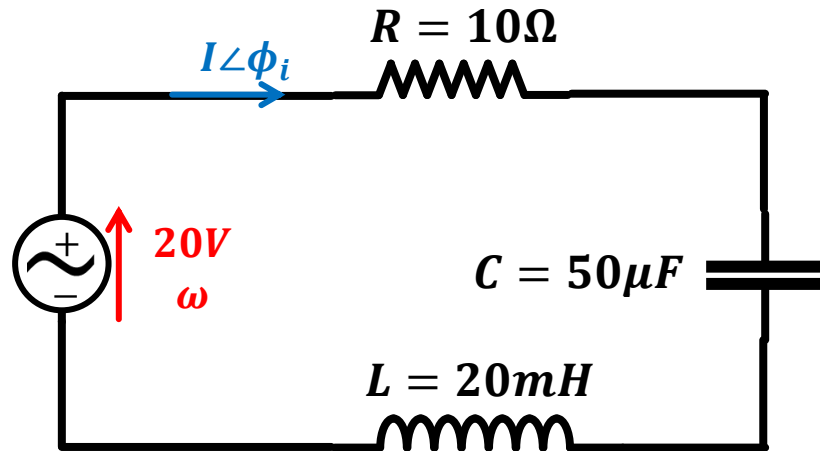
# Active v Reactive v Apparent Power







- We have seen that inductor and capacitor **individually contribute** to delaying and advancing (respectively) the current waveform w/r/t the voltage
  - When the inductance and capacitance value are equal (and opposite, inherently) they **nullify** each other – **Resonance**
  - $Z_L = j\omega L$  **increases** with **increasing frequency**
  - $Z_C = \frac{1}{j\omega C}$  **decreases** with **increasing frequency**
- 
- We did this example earlier with frequency ( $50\text{ Hz}$ ), we saw that the **overall circuit was capacitive** (i.e., capacitance was overpowering inductance and resultant current was  $80^\circ$  leading)
  - What happens if we **increase the frequency**?
  - There will come a frequency when **inductance just matches capacitance** – this is **resonance**
  - When this happens, you will be left with a **purely resistive circuit**, i.e., **overall impedance drops!**
  - As you increase the frequency (from  $50\text{ Hz}$ ), you would see current rising gradually, then sharply at resonance, then again start falling



$$Z_L = Z_C$$

$$j\omega L = \frac{1}{j\omega C}$$

$$\omega = \frac{1}{\sqrt{LC}}$$

$$\omega = \frac{1}{\sqrt{20 \times 10^{-3} \times 50 \times 10^{-6}}} = \frac{1}{\sqrt{10^{-6}}}$$

$$\omega_{res} = 1000 \frac{\text{rad}}{\text{s}}$$

Lets find out the current at resonant frequency and plot the phasor diagram

$$Z_L = j\omega_{res}L = j \times 1000 \times 20 \times 10^{-3} = j20\Omega$$

$$Z_C = \frac{1}{j\omega_{res}C} = \frac{-j}{1000 \times 50 \times 10^{-6}} = -j20\Omega$$

The **three elements** are clearly in **series**

$$Z = Z_R + Z_L + Z_C = 10 + j(20 - 20) = 10\Omega$$

Applying **Ohm's Law**

$$I = \frac{V}{Z} = \frac{20\angle 0^\circ}{10\angle 0^\circ} = 2\angle 0^\circ A$$

2 A is significantly higher than 343 mA that we calculated at 50 Hz frequency

This is because the at resonance, inductive and capacitive impedances nullify each other



## Example 1

A coil is connected to a 50 V AC supply at 400 Hz. If the current supplied to the coil is 200 mA and the coil has a resistance of 60  $\Omega$  , determine the value of inductance.

Like most practical forms of inductor, the coil in this example has both resistance *and* reactance. We can find the impedance of the coil from:

$$|Z| = \frac{V}{I} = \frac{50}{0.2} = 250\Omega$$

Since

$$|Z| = \sqrt{R^2 + X^2}$$

$$X = \sqrt{|Z|^2 - R^2}$$

$$X = \sqrt{250^2 - 60^2} = 243\Omega$$

Now since  $XL = 2\pi fL$ ,

$$L = \frac{X}{2\pi f} = \frac{243}{100\pi} = 0.097H$$



## Example 2

An AC load has a power factor of 0.8. Determine the active power dissipated in the load if it consumes a current of 2 A at 110 V.

Since active power

$$P = PF \times V_{rms} \times I_{rms}$$

$$P = 0.8 \times 110 \times 2$$

$$P = 176 \text{ W}$$

## Example 3

A coil having an inductance of  $150\text{ mH}$  and resistance of  $250\ \Omega$  is connected to a  $115\text{ V}$   $400\text{ Hz}$  AC supply. Determine:

- the power factor of the coil
- the current  $I_{rms}$  taken from the supply
- the power dissipated as heat in the coil.

(a) First we must find the reactance of the inductor,  $X_L$ , and the impedance,  $Z$ , of the coil at  $400\text{ Hz}$ .

$$X_L = 2\pi \times 400 \times 0.015 = 376\ \Omega$$

Thus

$$Z = R + jX_L = 250 + j376\ \Omega$$

The power factor is

$$\cos\gamma = \frac{R}{|Z|}$$

Since

$$|Z| = \sqrt{R^2 + X_L^2} = \sqrt{250^2 + 376^2} = 452\ \Omega$$

Thus  $\cos\gamma = \frac{R}{|Z|} = \frac{250}{452} = \mathbf{0.553}$

(b)

$$I_{rms} = \frac{V_{rms}}{|Z|} = \frac{115}{452} = \mathbf{0.254\text{ A}}$$

(c) The power dissipated as heat is the active power

$$P = V_{rms}I_{rms} \cos\gamma = 0.254 \times 115 \times 0.553$$
$$\mathbf{P = 16.15\text{ W}}$$



- Fundamentals of **Alternating Current – or AC**
  - DC v AC circuit study – waveforms a **function of time!**
  - **Sinusoidal** waveform – voltage & current
  - **Complex Numbers**
- AC circuits
  - **Phasor** study – simple way to solve time-varying circuits
  - Resistor, Inductor, Capacitor in phasor form - **CIVIL**
  - **Reactance** – Purely reactive circuits (just inductor/capacitor)
  - **Impedance** – Resistance & Reactance
- Power in AC circuits
  - **Active v Reactive v Apparent Power**
  - **Power Factor**
  - **Resonance**



# Attendance



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