

Solutions to Exercise Sheet 5

Q5.1 – see Seminar 3 slides for full details. Summary:

a) $f = 50 \text{ Hz}$, $p = 2$ pairs of poles, $n_s = 60 f/p = 60 \times 50/2 = 1500 \text{ rev min}^{-1}$

b) Line-to-line voltage V_L is 400V. Motor is star connected so each phase sees line-to-phase (phase) voltage $V_p = V_L/\sqrt{3} = 400/\sqrt{3} = 230.9 \text{ V}$

c) $R_R = 4\Omega$, $X_R = 16\Omega$ referred to stator. At onset of stall $s = a = R_R/X_R = 4/16 = 0.25$

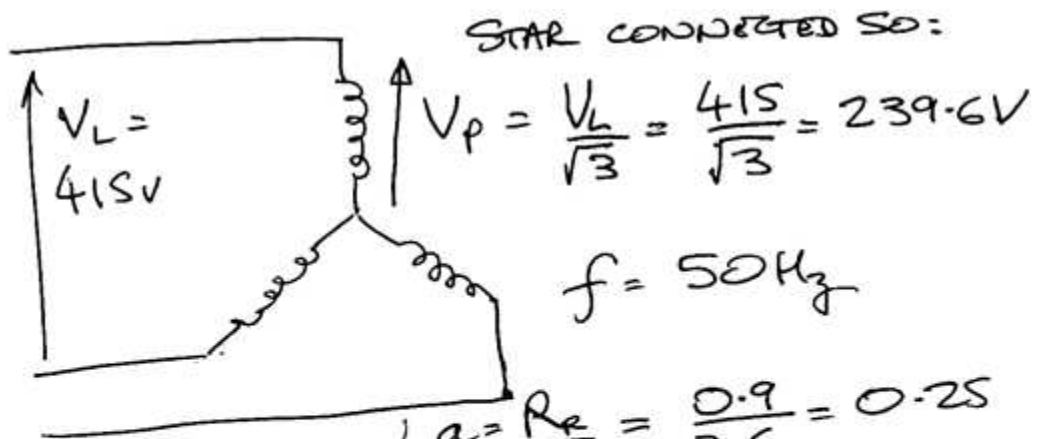
$$T = \frac{3p}{2\pi f} \times \frac{V^2 a s}{X_R (a^2 + s^2)} = \frac{3 \times 2}{2\pi \times 50} \times \frac{230.9^2 \times 0.25 \times 0.25}{16(0.25^2 + 0.25^2)} = 31.8 \text{ Nm}$$

d) $s = (1500 - 1430)/1500 = 0.0467$

$$T = \frac{3p}{2\pi f} \times \frac{V^2 a s}{X_R (a^2 + s^2)} = \frac{3 \times 2}{2\pi \times 50} \times \frac{230.9^2 \times 0.25 \times 0.0467}{16(0.25^2 + 0.0467^2)} = 11.49 \text{ Nm}$$

e) This point leads into Lecture 7 which includes discussion of variable-frequency inverters which change the synchronous speed of the motor and hence the running speed.

5.2



a) $s_{LIP} = 0.04 = s$ } $a = \frac{R_R}{X_R} = \frac{0.9}{3.6} = 0.25$
 $n_s = \frac{60f}{p}$ } 6 POLES \rightarrow 3 PAIRS OF POLES
 $\Rightarrow p = 3$

$$= \frac{60 \times 50}{3} = 1000 \text{ rev min}^{-1}$$

$$\Rightarrow n = n_s(1-s) = 1000(1-0.04) = 960 \text{ rev min}^{-1}$$

$$T = \frac{3p}{2\pi f} \times \frac{V^2 a s}{X_R (a^2 + s^2)}$$

$$= \frac{3 \times 3}{2\pi \times 50} \times \frac{239.6^2 \times 0.25 \times 0.04}{3.6(0.25^2 + 0.04^2)}$$

$$= 71.3 \text{ Nm}$$

$$\omega = \frac{2\pi n}{60} = \frac{2\pi \times 960}{60} = 100.53 \text{ rad s}^{-1}$$

$$\Rightarrow P = T\omega = 71.3 \times 100.53 = 7168 \text{ W} = 7.17 \text{ kW}$$

$$b) T = \frac{3p}{2\pi f} \times \frac{V^2 a s}{X_r(a^2 + s^2)} \quad \left. \vphantom{T} \right\} \text{ AT STARTUP } n=0$$

$$\Rightarrow S = \frac{n_s - 0}{n_s} = 1$$

$$= \frac{3 \times 3}{2\pi \times 50} \times \frac{239.6^2 \times 0.25 \times 1}{3.6 \times (0.25^2 + 1^2)}$$

$$= 107.5 \text{ Nm.}$$

5-3 $V_L = 220 \text{ V}$, FIND V_p FOR STAR CONN.

$$\Rightarrow V_p = \frac{V_L}{\sqrt{3}} = \frac{220}{\sqrt{3}} = 127 \text{ V}$$

$p = 3$ (6 POLES \rightarrow 3 PAIRS OF POLES), $f = 60 \text{ Hz}$

$$\Rightarrow n_s = \frac{60f}{p} = \frac{60 \times 60}{3} = 1200 \text{ rev min}^{-1}$$

$$a) n = 1160 \text{ rev min}^{-1} \Rightarrow S = \frac{n_s - n}{n_s} = \frac{1200 - 1160}{1200}$$

$$= 0.0333$$

$$R_e = 1.6 \Omega, X_r = 16 \Omega \Rightarrow a = \frac{R}{X_r} = \frac{1.6}{16} = 0.1$$

$$\Rightarrow T = \frac{3p}{2\pi f} \times \frac{V^2 a s}{X_r(a^2 + s^2)}$$

$$= \frac{3 \times 3}{2\pi \times 60} \times \frac{127^2 \times 0.1 \times 0.0333}{16 \times (0.1^2 + 0.0333^2)}$$

$$= 7.22 \text{ Nm}$$

$$b) T = \frac{3p}{2\pi f} \times \frac{V^2 a s}{X_r(a^2 + s^2)}$$

BUT $T = 10 \text{ Nm}$
S IS UNKNOWN

RE-ARRANGE AS QUADRATIC IN S:

$$2\pi f T X_r s^2 - 3p V^2 a s + 2\pi f T X_r a^2 = 0$$

$$f = 60 \text{ Hz}, X_r = 16 \Omega, T = 10 \text{ Nm}, p = 3, a = 0.1,$$

$$V = 127 \text{ V}$$

$$\Rightarrow 60318 s^2 - 14516 s + 603.2 = 0$$

$$\Rightarrow S = \frac{14516 \pm \sqrt{14516^2 - 4 \cdot 60318 \cdot 603.2}}{2 \cdot 60318}$$

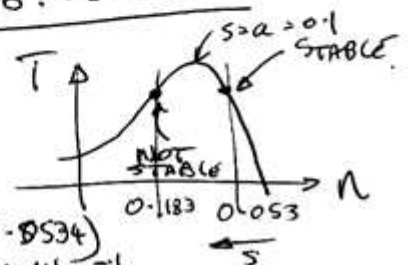
$$= 0.183 \text{ OR } 0.0534$$

$S > a$ SO
UNSTABLE

OK

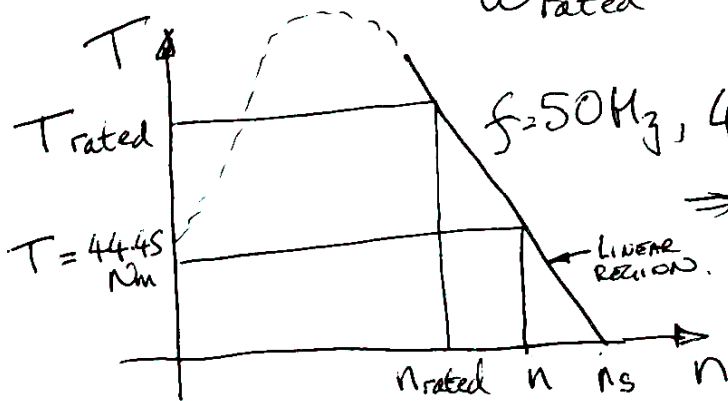
$$\Rightarrow n = n_s(1-s) = 1200(1-0.0534)$$

$$= 1136 \text{ rev min}^{-1}$$



5.4 Full-load speed = $n_{\text{rated}} = 1425 \text{ rev min}^{-1}$ ⁽³⁾
 $\Rightarrow \omega_{\text{rated}} = \frac{2\pi \times 1425}{60} = 149.2 \text{ Nm}$

$\Rightarrow T_{\text{rated}} = \frac{P_{\text{rated}}}{\omega_{\text{rated}}} = \frac{9625}{149.2} = 64.51 \text{ Nm}$



$f = 50 \text{ Hz}$, 4-pole so $p = 2$

$\Rightarrow n_s = \frac{60f}{p} = \frac{60 \times 50}{2} = 1500 \text{ rev min}^{-1}$

$n = n_s - \frac{T}{T_{\text{rated}}} \times (n_s - n_{\text{rated}})$

$= 1500 - \frac{44.45}{64.51} \times (1500 - 1425)$

$= 1448.3 \text{ rev min}^{-1}$

(NOTE: COMPARE WITH "EXACT" PROBLEM IN Q5: SOLUTION IS $1450 \text{ rev min}^{-1}$)

5.5 $V = V_p = \frac{V_L}{\sqrt{3}} = \frac{415}{\sqrt{3}} = 239.6 \text{ V}$

4-pole so $p = 2$
 $n_s = \frac{60f}{p} = \frac{60 \times 50}{2} = 1500 \text{ rev min}^{-1}$

a) $n = 1425 \Rightarrow s = \frac{n_s - n}{n_s}$

$= \frac{1500 - 1425}{1500} = 0.05$

$a = \frac{R_r}{X_r} = \frac{0.8}{4} = 0.2$

$\Rightarrow T = \frac{3p}{2\pi f} \times \frac{V^2 a s}{X_r(a^2 + s^2)} = \frac{3 \times 2}{2\pi \times 50} \times \frac{239.6^2 \times 0.2 \times 0.05}{4(0.2^2 + 0.05^2)}$
 $= 64.5 \text{ Nm}$

But $\omega = 1425 \times \frac{2\pi}{60} = 149.22 \text{ rad s}^{-1}$

$\Rightarrow P = T\omega = 64.5 \times 149.22 = 9624 \text{ W}$

b) $n = 1450 \text{ rev min}^{-1} \Rightarrow s = \frac{1500 - 1450}{1500} = 0.0333$

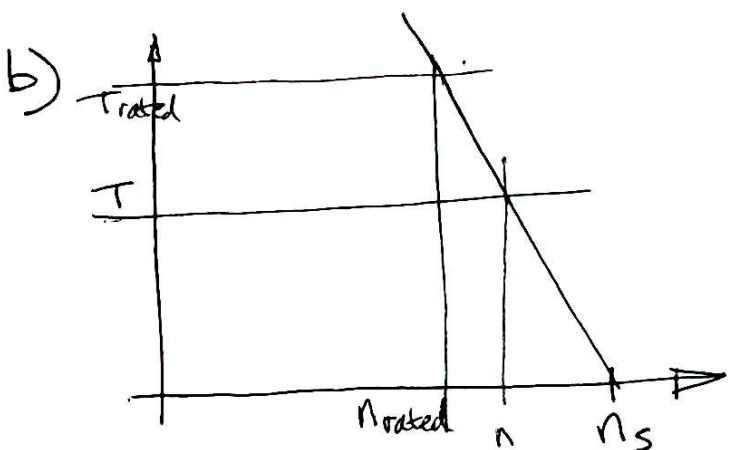
$\Rightarrow T = \frac{3p}{2\pi f} \times \frac{V^2 a s}{X_r(a^2 + s^2)} = \frac{3 \times 2}{2\pi \times 50} \times \frac{239.6^2 \times 0.2 \times 0.0333}{4(0.2^2 + 0.0333^2)} = 44.45 \text{ Nm}$

$\omega = 1450 \times \frac{2\pi}{60} = 151.84 \text{ rad s}^{-1} \Rightarrow P = T\omega = 44.45 \times 151.84 = 6719 \text{ W}$

5.6 a) $n_{rated} = 1450 \text{ rev min}^{-1}$

$\Rightarrow \omega_{rated} = \frac{n \times 2\pi}{60} = \frac{1450 \times 2\pi}{60} = 151.84 \text{ Nm}$

$\Rightarrow T_{rated} = \frac{P_{rated}}{\omega_{rated}} = \frac{3000}{151.84} = 19.76 \text{ Nm}$



ASSUME $n_s = 1500 \text{ rev min}^{-1}$
SINCE 50 Hz $\Rightarrow n_{rated} = 1450 \text{ rev min}^{-1}$

$n = n_s - \frac{T}{T_{rated}} \times (n_s - n_{rated})$ BUT $T = 15 \text{ Nm}$

$= 1500 - \frac{15}{19.76} \times (1500 - 1450) = 1462 \text{ rev min}^{-1}$

c) SEE NOTES NEAR END OF I.M. SECTION:
 $f = f_{rated} = 50 \text{ Hz}$, $T = 15 \text{ Nm}$ AS ABOVE
 $T_{rated} = 19.76 \text{ Nm}$ @ $1450 \text{ rev min}^{-1}$ AS ABOVE

PER PHASE: $V_{rated} = \frac{415}{\sqrt{3}} = 239.6$, $V = \frac{381}{\sqrt{3}} = 220 \text{ V}$

$n \approx n_s - \frac{T}{T_{rated}} \times \left(\frac{V_{rated}}{V}\right)^2 \left(\frac{f}{f_{rated}}\right) (n_s - n_{rated})$

$= 1500 - \frac{15}{19.76} \times \left(\frac{239.6}{220}\right)^2 \times (1500 - 1450)$

$= 1455 \text{ rev min}^{-1}$